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Name: Research on Vision System Calibration Method of Forestry Mobile Robots

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I declare that I received substantial, important, line by line peer review with several and substantial comments, important remarks and hints from, at least, 3 Reviewers and the Assistant Editor for my paper: Research on Vision System Calibration Method of Forestry Mobile Robots

with Authors: Ruting Yao, Yili Zheng, Fengjun Chen, Jian Wu, Hui Wang

I would like to thank all the reviewers for their thoughtful comments and efforts towards improving our manuscript. We revised the manuscript with special attention to the comments that we received from, at least, 3 reviewers that they were experts, specialist in the area of my paper.

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Date:2020.12.28

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