

# Vibrational comfort on board the vehicle: influence of speed bumps and comparison between different categories of vehicle

Vincenzo Barone, Domenico Walter Edvige Mongelli and Antonio Tassitani

**Abstract**—This paper shows the results of a study conducted on five different categories of vehicles in a specific test site. The aim was to investigate how the effect of the test site discontinuity determines variations of comfort related to the increase in speed and to the different class of vehicles. Measurements were obtained by combining data relating to vibrations in the three reference axes, detected through a vibration dosimeter (VIB-008), and geolocation data (latitude and longitude) identified by the GPS inside a smartphone. After the survey campaign it was determined a formulation that allows to define a Comfort Index CI depending on velocity and vehicle class. This study showed that the presence of speed bumps, in the test site investigated, appears to be uncomfortable even at speeds well below those required by the Highway Code.

**Keywords**—vibrational comfort, speed bump, comfort index.

## I. STATE OF ART

VIBRATIONS provoke different responses and sensations as a function of environmental conditions and user's physical state. Human responses to vibrations can be foreseen if they are measured and estimated in relation to the frequencies that have most influence on body reactions to stress; this requires knowledge of different parameters (eg. frequency, orthogonal axes direction, duration, etc.) as to define values representative of the true gravity of exposure [1].

Several methodologies have been introduced using differences of acceleration, of acoustic pressure and combinations of these [2], [3], [4], [5], [6], [7], [8], [9] through the use of smartphones or precision instruments, to detect abnormalities of road infrastructures. These methodologies, although using the same variables, do not identify values of comfort on board the vehicle, but allow to identify discontinuities of the road paving. As described [10] a body is considered "in vibration" if it describes an oscillating movement with respect to a specific reference system.

The level of vibration is determined by the square root of

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the instantaneous vibration corresponding to the time history measured on the whole body. The amount determined, represented in logarithmic scale, is defined as equivalent acceleration ( $a_{eq}$ ), whose value can be made dimensionless by means of the ratio between equivalent acceleration ( $a_{eq}$ ) and a reference value of  $10^{-6} \text{ m/s}^2$ . Other studies [11] propose a methodology to measure the comfort on public transport vehicles using an index called *Comfort Measuring System* CMS. The CMS system is comprised of three parts:

- Measurements obtained through the detection of smartphones' sensors;
- Database provided by operators of the transport system;
- Algorithm for the determination of results, using measurements from smartphones and from the database.

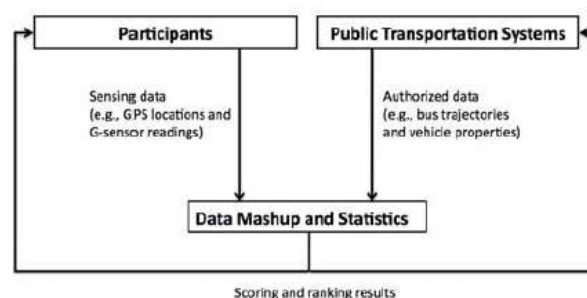


Fig. 1 The architecture of the CMS system [11]

According to ISO [12] acceptable values of vibration for the evaluation of comfort depend on many factors and specific analysis that are addressed. The same ISO [12] defines values to determine levels of comfort on public transport vehicles.

Values, however, depend on different variables, including the type of activity that passenger plays during the trip (reading, eating, writing, etc.) and other factors related to the environmental conditions inside the vehicles. In particular, the ISO 2631 defines specific classes of comfort/discomfort:

- Less than  $0.315 \text{ m/s}^2$  – not uncomfortable;
- $0.315 \text{ m/s}^2$  to  $0.63 \text{ m/s}^2$  – a little uncomfortable;
- $0.5 \text{ m/s}^2$  to  $1 \text{ m/s}^2$  – fairly uncomfortable;
- $0.8 \text{ m/s}^2$  to  $1.6 \text{ m/s}^2$  – uncomfortable;
- $1.25 \text{ m/s}^2$  to  $2.5 \text{ m/s}^2$  – very uncomfortable;
- greater than  $2 \text{ m/s}^2$  – extremely uncomfortable.

## II. INSTRUMENTATION

The instrumentation used in this work, to identify the comfort on board, is as follows:

- **Smartphone Samsung Galaxy S4 I9505:** to geolocalize information;
- **Vibration Dosimeter VIB 008:** to detect, according to the European Directive [13], the Band limit frequency-weighted RMS acceleration in  $\text{m/s}^2$  ( $a$ ) and the Frequency-weighted RMS acceleration,  $W_d$ ,  $W_k$ ,  $W_h$  filter, in  $\text{m/s}^2$  ( $a_w$ ), over the  $x$ ,  $y$ ,  $z$  axis, etc. The main features are shown in Figure 2. The analysis of data recorded by the VIB 008 has been realized with the software dB Master Ver.5.5, supplied by the manufacturer. This software allows to analyze and export data collected and stored by the instrument.

|                                                                             | Whole body mode                                                                                                                                                                                                                                              | Hand arm mode                                                                                                                                             |
|-----------------------------------------------------------------------------|--------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|-----------------------------------------------------------------------------------------------------------------------------------------------------------|
|                                                                             |                                                                                                                                                                             |                                                                          |
| Linearity domain                                                            | 70 dB                                                                                                                                                                                                                                                        | 70 dB                                                                                                                                                     |
| Dynamic range                                                               | 0.04-120 $\text{m/s}^2$                                                                                                                                                                                                                                      | 0.5-3000 $\text{m/s}^2$                                                                                                                                   |
| Frequency weightings                                                        | $W_d$ , $W_k$ , $1/1$ , $1/3$                                                                                                                                                                                                                                | $W_h$ , $1/1$ , $1/3$                                                                                                                                     |
| Broad-band weighting                                                        | 0.4 - 3700Hz                                                                                                                                                                                                                                                 |                                                                                                                                                           |
| Display resolution                                                          | 0.01                                                                                                                                                                                                                                                         | 0.01                                                                                                                                                      |
| Recorded magnitudes                                                         | Band-pass acceleration<br>Weighted acceleration<br>Band-pass and weighted peak and peak-to-peak acceleration<br>Peak factor<br>Equivalent acceleration<br>Daily exposure<br>Mobile RMS vibration MTVV<br>Vibration dose VDV<br>Seat efficiency SEAT (option) | Band-pass acceleration<br>Weighted acceleration<br>Band-pass and weighted peak and peak-to-peak acceleration<br>Equivalent acceleration<br>Daily exposure |
| Configuration                                                               | Transducers<br>Units $\text{m/s}^2$ , g<br>Integration time<br>Reference duration<br>Time constant                                                                                                                                                           | Transducers<br>Units $\text{m/s}^2$ , g<br>Integration time<br>Reference duration                                                                         |
| Alarm, overload counting                                                    | Yes                                                                                                                                                                                                                                                          | Yes                                                                                                                                                       |
| Calculated magnitudes                                                       | $A_v$ , $a_{eq}$ , $A(8)$ , $A(8)_v$ , VDV, $F_c$ , MTVV<br>SEAT(option)<br>Measurement time, calculation time                                                                                                                                               | $A_v$ , $A(8)$<br>Measurement time                                                                                                                        |
| Integration time                                                            | From 1s to 60s by steps of 1s                                                                                                                                                                                                                                | From 1s to 60s by steps of 1s                                                                                                                             |
| Spectrum (option)                                                           |                                                                                                                                                                                                                                                              |                                                                                                                                                           |
| Octave                                                                      | 1 Hz - 2kHz                                                                                                                                                                                                                                                  | 1Hz - 2kHz                                                                                                                                                |
| 1/3 octave                                                                  | 0.8Hz- 2.5kHz                                                                                                                                                                                                                                                | 0.8Hz- 2.5kHz                                                                                                                                             |
| Signal mode (option)                                                        |                                                                                                                                                                                                                                                              |                                                                                                                                                           |
| Sampling frequency                                                          | 256-8192Hz                                                                                                                                                                                                                                                   | 256-8192Hz                                                                                                                                                |
| Pre-trigger                                                                 | Depends on the calibration frequency<br>From 0 s to 16 s                                                                                                                                                                                                     | Depends on the calibration frequency<br>From 0 s to 16 s                                                                                                  |
| Maximum duration                                                            | -                                                                                                                                                                                                                                                            | -                                                                                                                                                         |
| Post-trigger                                                                | -                                                                                                                                                                                                                                                            | -                                                                                                                                                         |
| Operating temperature: $-10^\circ\text{C}$ / $+50^\circ\text{C}$ (0-95% RH) |                                                                                                                                                                                                                                                              |                                                                                                                                                           |

Fig. 2 Technical characteristics of VIB 008 Vibration Dosimeter (User Manual VIB 008 – 01dB)

## III. 4. METHODOLOGY

The vehicles used to determine comfort on board are:

- **Alfa Romeo Giulietta 2.0 140 CV** (sport sedan);
- **Land Rover Freelander 2.2 160 CV** (SUV);
- **Opel Zafira Tourer 2.0 160 CV** (minivan);
- **Ford Fiesta 1.4 96 CV** (compact car);
- **Opel Insignia 2.0 160 CV** (sedan).

The vibration dosimeter was positioned, with appropriate orientation (Figure 3), on the driving seat (Figure 4), in order to determine vibrations suffered by the spine while driving and caused by the presence of potholes, speed bumps or other road abnormalities.

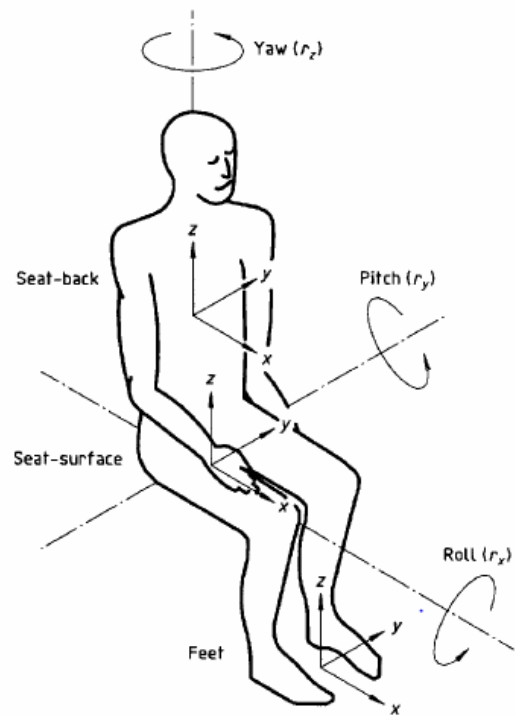


Fig. 3 Accelerations suffered from a body by sitting



Fig. 4 Positioning accelerometer VIB on the seat

Parameters used to determine comfort on board are: the  $a_w$  (frequency-weighted RMS acceleration ( $W_d$ ,  $W_k$ ,  $W_h$  filters) in  $\text{m/s}^2$ , along the three axis  $x$ ,  $y$ ,  $z$ ), determined by the mathematical formulation (1) and the  $a_v$ , Overall whole-body vibration acceleration, determined by the mathematical formulation (2):

$$a_w = \left[ \frac{1}{T} \cdot \int_0^T a_w^2(t) dt \right]^{0.5} \quad (1)$$

where:

- $a_w(t)$ : is the weighted acceleration (translational or rotational) as a function of time (time history), in metres per second squared ( $m/s^2$ );
- $T$ : measurement duration, in second.

$$a_v = \left[ (k_x \cdot a_{wx})^2 + (k_y \cdot a_{wy})^2 + (k_z \cdot a_{wz})^2 \right]^{0.5} \quad (2)$$

where:

- $a_{wx}$ ,  $a_{wy}$  and  $a_{wz}$  are the weighted r.m.s. accelerations with respect to the orthogonal axes  $x$ ,  $y$ ,  $z$ , respectively;
- $k_x$ ,  $k_y$ ,  $k_z$  are multiplying factors with respect to the orthogonal axes  $x$ ,  $y$ ,  $z$ , respectively. The multiplying factors value are:  $k_x=1.4$ ,  $k_y=1.4$  and  $k_z=1$ .

The use of these parameters has allowed to create a link between the traveling speed and the same parameter  $a_v$ , resulting in a *Comfort Index* (CI). This index is a function, as shown by the equation (3), of type of vehicle and speed.

$$CI(a_v) = a_v(T_{y0}; T_{yv}; v) = T_{y0} \cdot \exp(T_{yv} \cdot v_m) \quad (3)$$

where:

- $a_v$  are Overall whole-body vibration acceleration;
- $T_{y0}$  is a overall whole-body vibration acceleration for  $v=0$  and for a type of vehicles,  $T_{yv}$  is a overall whole-body vibration acceleration for  $v \neq 0$  and for a type of vehicles;
- $v_m$  is the average speed of the vehicle.

Once identified the value of CI, some reference thresholds were chosen to determine the vibrational comfort degree inside the vehicle:

- if CI less than  $0.315 m/s^2$ : not uncomfortable;
- if CI =  $0.315 m/s^2 - 0.565 m/s^2$ : a little uncomfortable;
- if CI =  $0.565 m/s^2 - 0.9 m/s^2$ : fairly uncomfortable;
- if CI =  $0.9 m/s^2 - 1.425 m/s^2$ : uncomfortable;
- if CI =  $1.425 m/s^2 - 2.25 m/s^2$ : very uncomfortable;
- if CI greater than  $2.25 m/s^2$ : extremely uncomfortable.

#### IV. EXPERIMENTS AND RESULTS

Instrumental analysis were carried out along a stretch of road, in excellent condition and with a length of about 5.0 Km, with a not homogeneous road paving because of the presence of stone artificial bumps.

The test site is located in the City of Rende (Cosenza) along the Viale Principe (Figure 5).

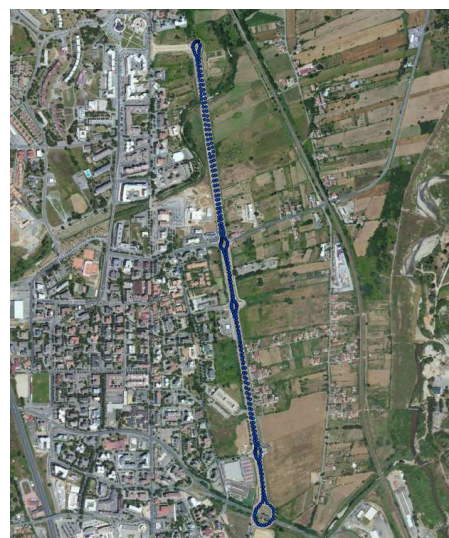


Fig. 5 Test site

Five different categories of vehicles were used for the instrumental analysis, for each of which 15 measurements were made, in order to have a significant statistical relevance.

Data collected by the instrument, in any survey, were exported through the software Maestro 5.5 dB (Figure 6).

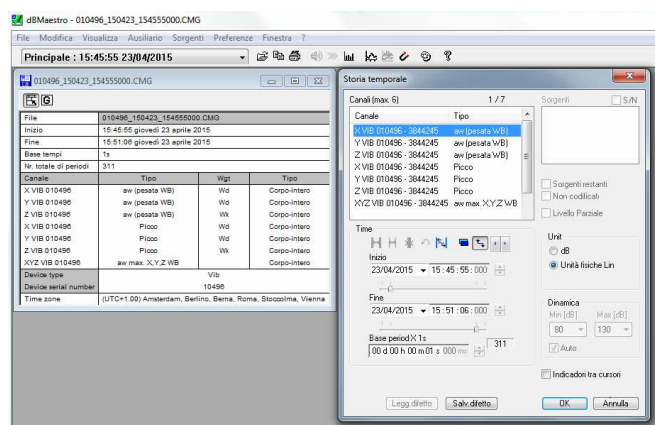


Fig. 6 dBMaestro Screenshot for exporting data

For each class of vehicle and for each measurements, the value of  $a_v$  was determined. Then the model was calibrated by means of an exponential regression, described by the equation (3), determining coefficients of dependent variables for each vehicle class useful to determine CI (Table 1).

Tab. 1 Determination of coefficients of CI for vehicle class

| Type of vehicle | $T_{y0}$ | $T_{yv}$ |
|-----------------|----------|----------|
| SUV             | 0.0638   | 0.0585   |
| Sport sedan     | 0.0688   | 0.0589   |
| Sedan           | 0.0588   | 0.0628   |
| Compact car     | 0.0611   | 0.0643   |
| Minivan         | 0.0694   | 0.0595   |

For each of the five categories of vehicle, it is determined

the graph linking the traveling speed and the comfort index CI.

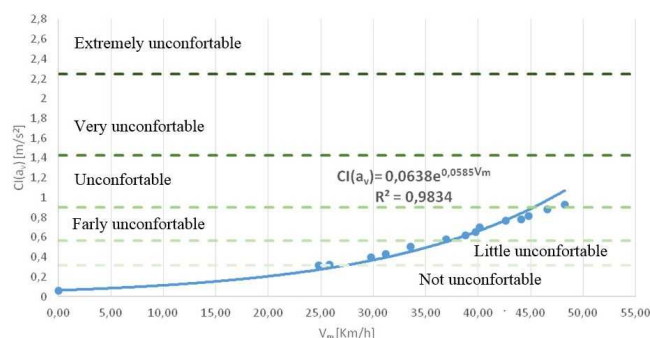


Fig. 7 CI Trend for Land Rover Freelander

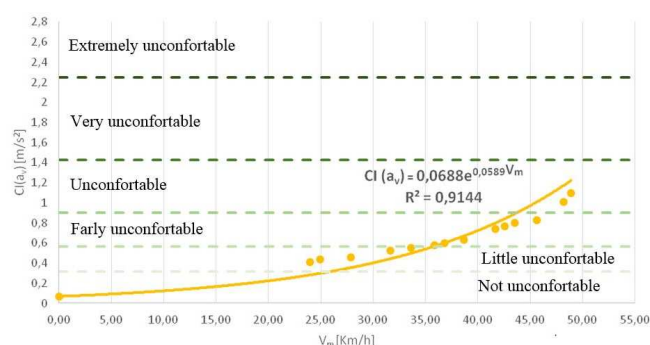


Fig. 8 CI Trend for Alfa Romeo Giulietta

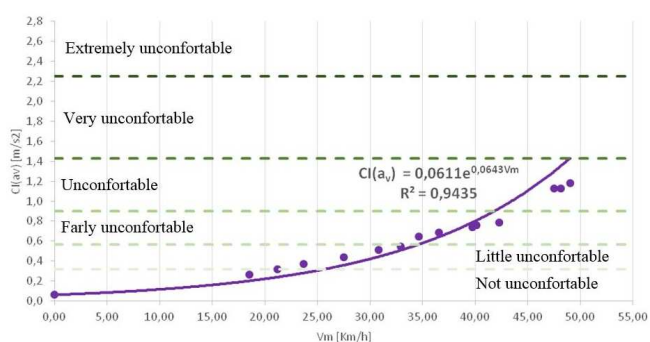


Fig. 9 CI Trend for Ford Fiesta

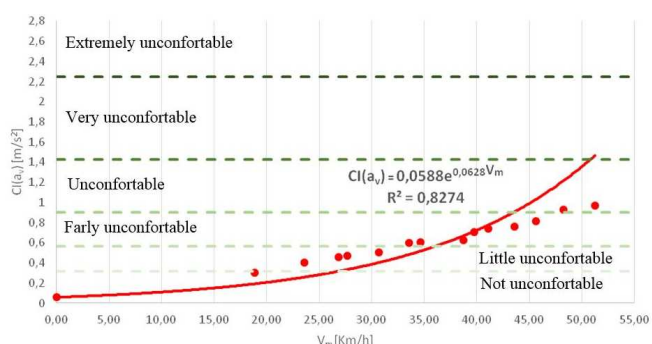


Fig. 10 CI Trend for Opel Insignia

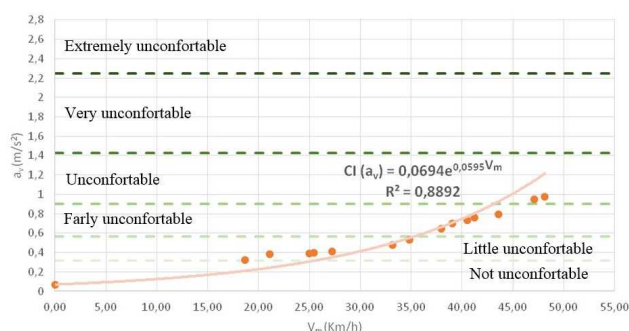


Fig. 11 CI Trend for Opel Zafira Tourer

Figures 7, 8, 9, 10, 11 show the trend of Comfort Index varying the traveling speed and the type of car. As can be seen from the value of  $R^2$ , for each type of car, the reliability of the exponential curve, which approximates the value of data obtained in the 15 measurements, is extremely high.

In order to have a more complete and clear view of differences between the various vehicles, it is shown a graph summarizing the CI trend for each type.

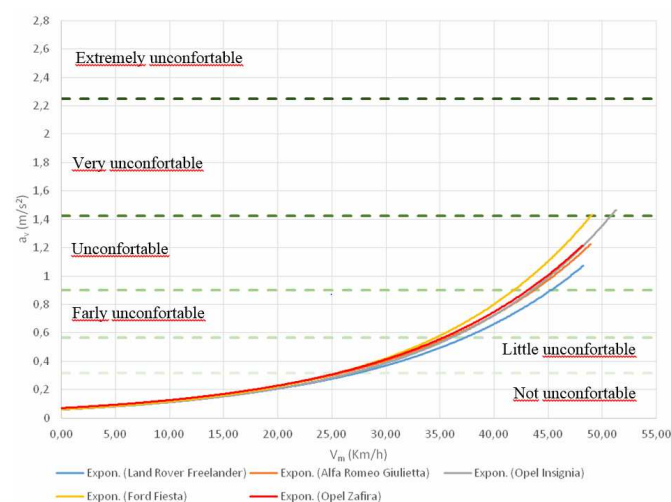


Fig. 12 General CI Trend

The figure 12, shows the CI Trend at different speed for all types of vehicle, highlighting some differences between the same types of vehicle. In fact, at low speeds the most comfortable vehicle is the sedan (Opel Insignia), however at high speeds the most comfortable vehicle is the SUV (Land Rover Freelander).

## V. CONCLUSIONS

The user interprets the quality of road track through perceptions, often subjective, resulting in one of the possible variables of route selection.

The definition of Comfort Index CI allows to identify a measure of quality of the road track and can be a parameter for choosing the path. This study has identified an evaluation criterion of Comfort Index (CI) specific for vehicle class and travel speed. Some reference thresholds and six classes of

vibrational comfort were also identified.

Starting from the analysis carried out on the test site, it was estimated that for speeds over 37 km/h, for each vehicle class, the road track results “*Farly Uncomfortable*”; also for speeds over 45 km /h the road track results “*Uncomfortable*”.

Therefore, while driving at speeds far below the maximum limit allowed by the Highway Code, in reference to all the five vehicle classes the road track results “*Uncomfortable*”.

Therefore, even if traveling at speeds well below the maximum limit allowed by the Highway Code, for all the five vehicle classes the track turns uncomfortable.

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