Delta – Open Sets And Delta – Continuous Functions

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Abstract—In 1968 Velicko [30] introduced the concepts of δ -closure and δ – int erior operations. We introduce and study properties of δ -derived, δ -border, δ -frontier and δ -exterior of a set using the concept of δ -open sets. We also introduce some new classes of topological spaces in terms of the concept of $\delta - D - sets$ and investigate some of their fundamental properties. Moreover. we investigate and study some further properties of the well-known notions of δ -closure and δ -interior of a set in a topological space. We also introduce $\delta - R_0$ space and study its characteristics. We also introduce $\delta - R_a$ space and study its characteristics. We introduce δ – *irresolute*, δ – closed, pre – δ – open and $pre - \delta - closed$ mappings and investigate properties and characterizations of these new types of mappings and also explore further properties of the well-known notions of δ -continuous and δ -open mappings.

Keywords—**Pure Mathematics**, **Topology**

I. INTRODUCTION AND PRELIMINARIES

Velicko [30] introduced the notion of δ -closure, and δ -interior operations. Throughout this paper, (X, τ) (simply X) always mean topological space on which no separation axioms are assumed unless explicitly stated. Let S be a subset of X. The closure (resp., interior) of S will be denoted by Cl(S), (resp., Int(S)). A subset S of X is called a semi-open set [21] if $S \subseteq Cl[Int(S)]$. The complement of a semi-open set is called a semiclosed set. The intersection of all semi-closed sets containing A is called the semi-closure of A and is denoted by sCl(A). The family of all semi-open sets in a topological space (X, τ) will be denoted by $SO(X, \tau)$. A subset M(X)of a space X called a semi-neighborhood of a point $x \in X$ if there exists a semi-open set S such that $x \in S \subseteq M(x)$. In [19] Latif introduced the notion of semi-convergence of filters and investigated some characterizations related to semi-open continuous function. A point $x \in X$ is called the δ -cluster point of $A \subseteq X$ if AI $Int[Cl(U)] \neq \phi$ for every open set U of X containing x. The set of all δ -cluster points of A is called the δ -closure of A, denoted by $Cl_{\delta}(A)$. A subset $A \subseteq X$ is called δ -closed if $A = Cl_{\delta}(A)$. The complement of a δ -closed set is called δ -open. The collection of all δ -open sets in a topological space (X, τ) forms a topology au_{δ} on X, called the semigeneralization topology of τ , weaker than τ and the class of all regular open sets in τ forms an open basis for (X, τ_{δ}) . In this paper, we introduce and study properties of δ -derived, δ -border, δ -frontier and δ -exterior of a set using the concept of δ -open and study also other properties of the well-known notions of δ – *closure* and δ -int*erior*. The notion of θ – open subsets, θ – closed subsets and θ -closure were introduced by Velicko [30] for the purpose of studying the important class of

H-closed spaces arbitrary in terms of filterbases. A point $x \in X$ is called a θ -adherent point of A [7], if AI $Cl(V) \neq \phi$ for every open set V containing x. The set of all θ -adherent points of A is called the θ -closure of A and is denoted by $Cl_{\theta}(A)$. A subset A of X is called θ -closed if $A = Cl_{\theta}(A).$ Dontchev and Maki [7], Lemma 3.9 have shown that if A and B are subsets of a space $(X, \tau),$ then $Cl_{\theta}(A \cup B) = Cl_{\theta}(A) \cup Cl_{\theta}(B)$ and $Cl_{\theta}(AI B) = Cl_{\theta}(A)I Cl_{\theta}(B)$. Note also that the θ -closure of a given set need not be a θ -closed set. But it is always closed. The complement of a θ -closed set is called a θ -open set. The θ -interior of set A in X, written $Int_{\theta}(A)$, consists of those points x of A such that for some open set U containing x, $Cl(U) \subseteq A$. A set A is θ -open if and only if $A = Int_{\alpha}(A)$, or equivalently, X - A is θ -closed. The collection of all θ -open sets in a topological space (X, τ) forms a topology τ_a on X, weaker than τ . We observe that for any topological $(X, \tau),$ the relation space always holds. We also have $\tau_{\theta} \subseteq \tau_{\delta} \subseteq \tau$ $A \subseteq Cl(A) \subseteq Cl_{\delta}(A) \subseteq Cl_{\theta}(A)$, for any subset A of X.

2. BASIC PROPERTIES AND APPLICATIONS OF

DELTA OPEN SETS

Definition 1.1. Let *A* be a subset of a topological space (X, τ) . A point $x \in A$ is said to be a δ -*limit* point of *A* if for each δ -*open* set *U* containing *x*, $UI(A-\{x\}) \neq \phi$. The set of all δ -*limit* points of *A* is called the δ -*derived* set of *A* and is denoted by $D_{\delta}(A)$.

Theorem 1.2. For subsets A, B of a space X, the following statements hold:

(1) $D(A) \subseteq D_{\delta}(A)$, where D(A) is the derived set of A;

(2) If
$$A \subseteq B$$
, then $D_{\delta}(A) \subseteq D_{\delta}(B)$;
(3) $D_{\delta}(A) \cup D_{\delta}(B) = D_{\delta}(A \cup B)$ and
 $D_{\delta}(A \cup B) \subseteq D_{\delta}(A) \cup D_{\delta}(B)$;
(4) $[D_{\delta}(D_{\delta}(A)) - A] \subseteq D_{\delta}(A)$;
(5) $D_{\delta}[A \cup D_{\delta}(A)] \subseteq [A \cup D_{\delta}(A)]$.

Proof. (1) It suffices to observe that every δ -open set is an open set.

(2) Obvious.

(3) $D_{\delta}(A) \cup D_{\delta}(B) = D_{\delta}(A \cup B)$ is a modification of the standard proof for D, where open sets are replaced by δ -open sets. $D_{\delta}(A \cup B) \subseteq D_{\delta}(A) \cup D_{\delta}(B)$ follows by (2).

(4) If $x \in [D_{\delta}(D_{\delta}(A)) - A]$ and U is a $\delta - open$ set containing x, then $U \ I \ [D_{\delta}(A) - \{x\}] \neq \phi$. Let $y \in U \ I \ [D_{\delta}(A) - \{x\}]$. Then, since $y \in D_{\delta}(A)$ and $y \in U$, so $U \ I \ [A - \{y\}] \neq \phi$. Let $z \in U \ I \ [A - \{y\}]$. Then, $z \neq x$ for $z \in A$ and $x \notin A$. Hence, $U \ I \ [A - \{x\}] \neq \phi$. Therefore, $x \in D_{\delta}(A)$.

(5) Let $x \in D_{\delta}[A \cup D_{\delta}(A)]$. If $x \in A$, the result is obvious. So, let $x \in [D_{\delta}(A \cup D_{\delta}(A)) - A]$, then, for δ -open set Ucontaining *x*. $U \operatorname{I} \left[A \operatorname{U} D_{\delta}(A) - \{x\} \right] \neq \phi.$ Thus, $UI [A - \{x\}] \neq \phi$ or $UI [D_{\delta}(A) - \{x\}] \neq \phi$. Now, it follows similarly from (4) that $U \operatorname{I} \left[A - \{x\} \right] \neq \phi.$ Hence, $x \in D_{s}(A).$

Therefore, in any case, $D_{\delta}[A \cup D_{\delta}(A)] \subseteq [A \cup D_{\delta}(A)].$

Theorem 1.3. For any subset A of a space X, $Cl_{\delta}(A) = A \cup D_{\delta}(A).$

Proof. Since $D_{\delta}(A) \subseteq Cl_{\delta}(A)$, $A \cup D_{\delta}(A) \subseteq Cl_{\delta}(A)$. On the other hand, let $x \in Cl_{\delta}(A)$. If $x \in A$, then the proof is complete. If $x \notin A$, each δ -open set U containing xintersects A at a point distinct from x; so $x \in D_{\delta}(A)$. Thus, $Cl_{\delta}(A) \subseteq [A \cup D_{\delta}(A)]$, which completes the proof.

Corollary 1.4. A subset A is δ -closed if and only if it contains the set of its δ -limit it points.

Definition 1.5. A point $x \in X$ is said to be a δ -*interior* point of A if there exists a δ -*open* set U containing x such that $U \subseteq A$. The set of all δ -*interior* points of A is said to be δ -*interior* of A and is denoted by $Int_{\delta}(A)$.

Theorem 1.6. For subsets A, B of a space X, the following statements are true:

(1) $Int_{\delta}(A)$ is the largest δ -open set contained in A;

- (2) *A* is δ -*open* if and only if $A = Int_{\delta}(A)$;
- (3) $Int_{\delta}[Int_{\delta}(A)] = Int_{\delta}(A);$
- (4) $Int_{\delta}(A) = [A D_{\delta}(X A)];$
- $(5) \left[X Int_{\delta}(A) \right] = Cl_{\delta}(X A);$
- $(6) \left[X Cl_{\delta}(A) \right] = Int_{\delta}(X A);$
- (7) $A \subseteq B$, then $Int_{\delta}(A) \subseteq Int_{\delta}(B)$.

- (8) $Int_{\delta}(A) \cup Int_{\delta}(B) \subseteq Int_{\delta}(A \cup B);$
- (9) $Int_{\delta}(A \ B) = Int_{\delta}(A) \ Int_{\delta}(B);$

Proof. (4) If $x \in [A - D_{\delta}(X - A)]$, then $x \notin D_{\delta}(X - A)$ and so there exists a δ -open set U containing x such that $U I (X - A) = \phi$. Then, $x \in U \subseteq A$ and hence $x \in Int_{\delta}(A)$, that is, $[A - D_{\delta}(X - A)] \subseteq Int_{\delta}(A)$. On the other hand, if $x \in Int_{\delta}(A)$, then $x \notin D_{\delta}(X - A)$ since $Int_{\delta}(A)$ is δ -open and $[Int_{\delta}(A)I (X - A)] = \phi$. Hence, $Int_{\delta}(A) = [A - D_{\delta}(X - A)].$

(5)
$$X - Int_{\delta}(A) = X - [A - D_{\delta}(X - A)] =$$

 $(X - A)UD_{\delta}(X - A) = Cl_{\delta}(X - A)$

Definition 1.7. $Bd_{\delta}(A) = A - Int_{\delta}(A)$ is said to be the δ -border of A.

Theorem 1.8. For a subset A of a space X, the following statements hold:

(1) $Bd(A) \subseteq Bd_{\delta}(A)$ where Bd(A) denotes the border of A;

- (2) $A = Int_{\delta}(A) \cup Bd_{\delta}(A);$ (3) $Int_{\delta}(A) \cup Bd_{\delta}(A) = \phi;$
- (4) *A* is a δ -open set if and only if $Bd_{\delta}(A) = \phi$;
- (5) $Bd_{\delta}[Int_{\delta}(A)] = \phi;$ (6) $Int_{\delta}[Bd_{\delta}(A)] = \phi;$ (7) $Bd_{\delta}[Bd_{\delta}(A)] = Bd_{\delta}(A);$ (8) $Bd_{\delta}(A) = AI[Cl_{\delta}(X - A)];$ (9) $Bd_{\delta}(A) = D_{\delta}(X - A).$

Proof. (6) If $x \in Int_{\delta}[Bd_{\delta}(A)]$, then $x \in Bd_{\delta}(A)$. On the other hand, since $Bd_{\delta}(A) \subseteq A, x \in Int_{\delta}[Bd_{\delta}(A)] \subseteq Int_{\delta}(A)$. Hence, $x \in Int_{\delta}(A)$ I $Bd_{\delta}(A)$, which contradicts (3). Thus, $Int_{\delta}[Bd_{\delta}(A)] = \phi$.

(8)
$$Bd_{\delta}(A) = A - Int_{\delta}(A) = A - [X - Cl_{\delta}(X - A)] = AI Cl_{\delta}(X - A).$$

(9)
$$Bd_{\delta}(A) = A - Int_{\delta}(A) = A - [A - D_{\delta}(X - A)] = D_{\delta}(X - A).$$

Definition 1.9. $Fr_{\delta}(A) = Cl_{\delta}(A) - Int_{\delta}(A)$ is said to be the δ -*frontier* of A.

Theorem 1.10. For a subset A of a space X, the following statements hold:

(1) $Fr(A) \subseteq Fr_{\delta}(A)$ where Fr(A) denotes the frontier of A;

(2)
$$Cl_{\delta}(A) = Int_{\delta}(A) \cup Fr_{\delta}(A);$$

(3)
$$Int_{\delta}(A)I Fr_{\delta}(A) = \phi;$$

(4)
$$Bd_{\delta}(A) \subseteq Fr_{\delta}(A);$$

(5)
$$Fr_{\delta}(A) = Bd_{\delta}(A)UD_{\delta}(A);$$

(6) *A* is a δ -open set if and only if $Fr_{\delta}(A) = D_{\delta}(A);$

(7)
$$Fr_{\delta}(A) = Cl_{\delta}(A)I Cl_{\delta}(X-A);$$

(8)
$$Fr_{\delta}(A) = Fr_{\delta}(X - A);$$

(9)
$$Fr_{\delta}(A)$$
 is δ -closed;

(10)
$$Fr_{\delta}[Fr_{\delta}(A)] \subseteq Fr_{\delta}(A);$$

(11)
$$Fr_{\delta}[Int_{\delta}(A)] \subseteq Fr_{\delta}(A);$$

(12)
$$Fr_{\delta}[Cl_{\delta}(A)] \subseteq Fr_{\delta}(A);$$

(13) $Int_{\delta}(A) = A - Fr_{\delta}(A)$.

Proof. (2)
$$Int_{\delta}(A) \cup Fr_{\delta}(A) =$$

 $Int_{\delta}(A) \cup [Cl_{\delta}(A) - Int_{\delta}(A)] = Cl_{\delta}(A)$

(3)
$$Int_{\delta}(A)I \quad Fr_{\delta}(A) = Int_{\delta}(A)I \quad [Cl_{\delta}(A) - Int_{\delta}(A)] = \phi.$$

(5) Since
$$Int_{\delta}(A) \cup Fr_{\delta}(A) =$$

 $Int_{\delta}(A) \cup Bd_{\delta}(A) \cup D_{\delta}(A), Fr_{\delta}(A) = Bd_{\delta}(A) \cup D_{\delta}(A)$
(7) $Fr_{\delta}(A) = Cl_{\delta}(A) - Int_{\delta}(A) = Cl_{\delta}(A) \cup Cl_{\delta}(X - A).$

$$(9) Cl_{\delta} [Fr_{\delta}(A)] = Cl_{\delta} [Cl_{\delta}(A)I Cl_{\delta}(X-A)] \subseteq Cl_{\delta} [Cl_{\delta}(A)]I Cl_{\delta} [Cl_{\delta}(X-A)]$$

= $Cl_{\delta}(A)$ I $Cl_{\delta}(X-A) = Fr_{\delta}(A)$. Hence $Fr_{\delta}(A)$ is δ -closed.

(10)
$$Fr_{\delta}[Fr_{\delta}(A)] = Cl_{\delta}[Fr_{\delta}(A)]I \quad Cl_{\delta}[X - Fr_{\delta}(A)] \subseteq Cl_{\delta}[Fr_{\delta}(A)] = Fr_{\delta}(A)$$

$$(12) Fr_{\delta} [Cl_{\delta}(A)] = Cl_{\delta} [Cl_{\delta}(A)] - Int_{\delta} [Cl_{\delta}(A)] = Cl_{\delta}(A) - Int_{\delta} [Cl_{\delta}(A)] \subseteq [Cl_{\delta}(A) - Int_{\delta}(A)] = Fr_{\delta}(A).$$

(13)
$$A - Fr_{\delta}(A) = A - \left[Cl_{\delta}(A) - Int_{\delta}(A)\right] = Int_{\delta}(A).$$

Remark 1.11. Let *A* and *B* be subsets of *X*. Then $A \subseteq B$ does not imply that either $Fr_{\delta}(B) \subseteq Fr_{\delta}(A)$ or $Fr_{\delta}(A) \subseteq Fr_{\delta}(B)$.

Definition 1.12. $Ext_{\delta}(A) = Int_{\delta}(X - A)$ is said to be a δ -exterior of A.

Theorem 1.13. For a subset A of a space X, the following statements hold:

(1) $Ext_{\delta}(A) \subseteq Ext(A)$ where Ext(A) denotes the exterior of A;

(2) $Ext_{\delta}(A)$ is δ -opn; (3) $Ext_{\delta}(A) = Int_{\delta}(X-A) = X - Cl_{\delta}(A);$ (4) $Ext_{\delta} [Ext_{\delta}(A)] = Int_{\delta} [Cl_{\delta}(A)];$ (5) If $A \subseteq B$, then $Ext_{\delta}(B) \subseteq Ext_{\delta}(A)$; (6) $Ext_{\delta}(A \cup B) = Ext_{\delta}(A) \cup Ext_{\delta}(B);$ (7) $Ext_{\delta}(A)I Ext_{\delta}(B) \subseteq Ext_{\delta}(AI B);$ (8) $Ext_{\delta}(X) = \phi;$ (9) $Ext_{\delta}(\phi) = X;$ (10) $Ext_{\delta}(A) = Ext_{\delta}[X - Ext_{\delta}(A)];$ (11) $Int_{\delta}(A) \subseteq Ext_{\delta}[Ext_{\delta}(A)];$ (12) $X = Int_{\delta}(A) \cup Ext_{\delta}(A) \cup Fr_{\delta}(A);$ (13) $Ext_{\delta}(A)UExt_{\delta}(B) \subseteq Ext_{\delta}(AI B)$. **Proof.** (4) $Ext_{\delta} [Ext_{\delta}(A)] = Ext_{\delta} [X - Cl_{\delta}(A)] =$ $Int_{\delta} \left[X - \left(X - Cl_{\delta}(A) \right) \right] = Int_{\delta} \left[Cl_{\delta}(A) \right]$ (10) $Ext_{\delta} [X - Ext_{\delta}(A)] = Ext_{\delta} [X - Int_{\delta}(X - A)]$ $= Int_{\delta} \left[X - \left(X - Int_{\delta} \left(X - A \right) \right) \right]$ $= Int_{\delta} \left[Int_{\delta} (X - A) \right] = Int_{\delta} (X - A) = Ext_{\delta} (A).$ (11) $Int_{\delta}(A) \subseteq Int_{\delta} \lceil Cl_{\delta}(A) \rceil = Int_{\delta} \lceil X - Int_{\delta}(X - A) \rceil$ $= Int_{\delta} \left[X - Ext_{\delta}(A) \right] = Ext_{\delta} \left[Ext_{\delta}(A) \right].$ (13)

 $Ext_{\delta}(A) \cup Ext_{\delta}(B) = Int_{\delta}(X - A) \cup Int_{\delta}(X - B)$ $\subseteq Int_{\delta}[(X - A) \cup (X - B)]$ $= Int_{\delta}[X - (AI B)] = Ext_{\delta}(AI B).$

Definition 1.14. Let X be a topological space. A set $A \subseteq X$ is said to be δ -saturated if for every $x \in A$ it implies that $Cl_{\delta}(\{x\}) \subseteq A$. The class of all δ -saturated sets in X will be denoted by $B_{\delta}(X)$.

Theorem 1.15. Let X be a topological space. Then $B_{\delta}(X)$ is a complete Boolean set Algebra.

Proof. We will prove that all the unions and complements of elements of $B_{\delta}(X)$ are members of $B_{\delta}(X)$. Obviously, only the proof regarding the complements is not trivial. Let $A \in B_{\delta}(X)$ and suppose that $Cl_{\delta}(\{x\}) \not\subset (X - A)$ for some $x \in (X - A)$. Then there exists $y \in A$ such that $y \in Cl_{s}(\{x\})$. It follows that x and y have no disjoint neighborhoods. Then $x \in Cl_{\delta}(\{y\})$. But this is a contradiction, because by the definition of $B_{s}(X)$ we have $Cl_{\delta}(\{y\}) \subseteq A$. Hence, $Cl_{\delta}(\{x\}) \subseteq (X - A)$ for $x \in (X - A),$ which every implies $(X-A) \in B_{\delta}(X).$

Corrolary 1.16. $B_{\delta}(X)$ contains every union and every intersection of δ -*closed* and δ -*open* sets in *X*.

Definition 1.17. A space X is said to be δ -Hausdorff if for every $x \neq y \in X$, there exist δ -*open* sets U_x , V_y such that $x \in U_x$, $y \in V_y$ and $U_x \parallel V_y = \phi$.

Theorem 1.18. Let (X, τ) be a topological space. Then the following statements are equivalent:

(1) X is $\delta - T_2$;

(2) Let $x \in X$. For each $y \neq x$, there exists a δ -open set U such that $x \in U$ and $y \notin Cl_{\delta}(U)$;

(3) For each
$$x \in X$$
,
I $\{Cl_{\delta}(U) | U \in \tau_{\delta} \text{ and } x \in U\} = \{x\};$

(4) The diagonal $\Delta = \{(x, x) | x \in X\}$ is a δ -closed set in $X \times X$.

Proof. (1) \Rightarrow (2): Let $x \in X$ and $y \neq x$. Then there are disjoint δ -*open* sets U and V such that $x \in U$ and $y \in V$. Clearly, V^c is δ -*closed*, $Cl_{\delta}(U) \subseteq V^c$, $y \notin V^c$ and therefore $y \notin Cl_{\delta}(U)$.

(2) \Rightarrow (3). If $y \neq x$, there exists a δ -open set U such that $x \in U$ and $y \notin Cl_{\delta}(U)$. So $y \notin I \{Cl_{\delta}(U) | U \in \tau_{\delta} \text{ and } x \in U\}.$

(3) \Rightarrow (4). We prove that Δ^c is δ -open. Let $(x, y) \notin \Delta$. Then $y \neq x$ and since I $\{Cl_{\delta}(U) | U \in \tau_{\delta} \text{ and } x \in U\} = \{x\}$ there is some $U \in \tau_{\delta}$ with $x \in U$ and $y \notin Cl_{\delta}(U)$. Since $U I [Cl_{\delta}(U)]^c = \phi, \quad U \times [Cl_{\delta}(U)]^c$ is a δ -open set such that $(x, y) \in U \times [Cl_{\delta}(U)]^c \subseteq \Delta^c$.

(4) \Rightarrow (1). If $y \neq x$, then $(x, y) \notin \Delta$ and thus there exist δ -*open* sets *U* and *V* such that $(x, y) \in U \times V$ and $(U \times V)$ I $\Delta = \phi$. Clearly, for the δ -*open* sets *U* and *V* we have: $x \in U, y \in V$ and *U* I $V = \phi$.

Definition 1.19. A subset A of a space X is said to be δ -compact if every cover of X by δ -open sets has a finite subcover.

It is well-known that every closed subset of a compact space is compact. The next theorem approximates this result for δ -compactness.

Theorem 1.20. A δ -compact subset of a δ -Hausdorff space is δ -closed.

Proof. Let A be a δ -compact subset of a δ -Hausdorff space X. We will show that

(X-A) is δ -open. Let $x \in (X-A)$. Then for each $a \in A$ there exist δ -open sets $U_{x,a}$ and V_a such that $x \in U_{x,a}$ and $a \in V_a$ and $U_{x,a}$ I $V_a = \phi$. The collection $\{V_a | a \in A\}$ is a δ -open cover of A. Therefore, there exists a finite subcollection $\{V_{a_k} | k = 1, 2, 3, ..., n\}$ that covers A. Let $U_x = I \{U_{x,a_k} | k = 1, 2, 3, ..., n\}$. Then $x \in U_x$, U_x is δ open and U_x I $A = \phi$. This proves that A is δ -closed.

Theorem 1.21. A δ -*closed* subset of a δ -Hausdorff space is δ -*compact*.

Proof. Let X be δ -compact and let A be a δ -closed subset of X. Let Γ be a δ -open cover of A. Then $\Gamma^* = \Gamma \cup \{X - A\}$ is a δ -open cover of X. Since X is δ -compact, this collection Γ^* has a finite collection Λ^* that covers X. But then Γ ha a finite subcollection $\Lambda = \Lambda^* - \{X - A\}$ that covers A as we need.

Definition 1.22. Let A be a subset of a topological space X. Then $\delta - kernel$ of A, denoted by $Ker_{\delta}(A) = I \{ O \in \tau_{\delta} | A \subseteq O \}.$

Definition 1.23. Let x be a point of a topological space X. Then δ -kernel of x, denoted by $Ker_{\delta}(\{x\})$ is defined to be the set $Ker_{\delta}(\{x\}) = I \{ O \in \tau_{\delta} | x \in O \}.$

Lemma 1.24. Let (X, τ) be a topological space and $x \in X$. Then $Ker_{\delta}(A) = \{x \in X | Cl_{\delta}(\{x\}) | A \neq \phi\}.$

Proof. Let $x \in Ker_{\delta}(A)$ and $Cl_{\delta}(\{x\})I A = \phi$. Hence $x \notin [X - Ker_{\delta}(\{x\})]$ which is a $\delta - open$ set containing A. This is impossible, since $x \in Ker_{\delta}(A)$. Consequently, $Cl_{\delta}(\{x\})I A \neq \phi$. Let $Cl_{\delta}(\{x\})I A \neq \phi$ and $x \notin Ker_{\delta}(A)$. Then there exists a $\delta - open$ set D containing A and $x \notin D$. Let $y \in Cl_{\delta}(\{x\})$ I *A*. Hence, *D* is a δ -*open* neighborhood of *y* with $x \notin D$. By this contradiction, $x \in Ker_{\delta}(A)$ and the claim.

Definition 1.25. A topological space (X, τ) is said to be a $\delta - R_0$ space if every δ -open set contains the δ -closure of each of its singletons.

Lemma 1.26. Let (X, τ) be a topological space and $x \in X$. Then $y \in Ker_{\delta}(\{x\})$ if and only if $x \in Ker_{\delta}(\{y\})$.

Proof. Suppose that $y \notin Ker_{\delta}(\{x\})$. Then there exists a δ -*open* set V containing x such that $y \notin V$. Therefore we have $x \notin Cl_{\delta}(\{y\})$. The proof of the converse case can be done similarly.

Lemma 1.27. The following statements are equivalent for any points x and y in a topological space (X, τ) :

(1)
$$Ker_{\delta}(\{x\}) \neq Ker_{\delta}(\{y\});$$

(2)
$$Cl_{\delta}(\lbrace x \rbrace) \neq Cl_{\delta}(\lbrace y \rbrace).$$

Proof. $(1) \Rightarrow (2):$ Suppose that $Ker_{\delta}(\{x\}) \neq Ker_{\delta}(\{y\})$. Then there exists a point z in X such that $z \in Ker_{\delta}(\{x\})$ and $z \notin Ker_{\delta}(\{y\})$. It follows from $z \in Ker_{\delta}(\{x\})$ $\{x\}$ I $Cl_{\delta}(\{x\}) \neq \phi$. This implies that that $x \in Cl_{\delta}(\{z\})$. By $z \notin Ker_{\delta}(\{y\})$, we have $\{y\}$ I $Cl_{\delta}(\{z\}) = \phi$. Since $x \in Cl_{\delta}(\{z\})$ and $Cl_{\delta}(\{x\}) \subseteq Cl_{\delta}(\{z\})$. Hence $\{y\} I Cl_{\delta}(\{x\}) = \phi$. Therefore, $Cl_{\delta}(\{x\}) \neq Cl_{\delta}(\{y\})$.

(2) \Rightarrow (1): Suppose that $Cl_{\delta}(\{x\}) \neq Cl_{\delta}(\{y\})$. Then there exists a point $z \in X$ such that $z \in Cl_{\delta}(\{x\})$ and $z \notin Cl_{\delta}(\{y\})$. Then, there exists a δ -open set containing z and therefore x but not y, i.e., $y \notin Ker_{\delta}(\{x\})$. Hence $Ker_{\delta}(\{x\}) \neq Ker_{\delta}(\{y\})$.

Theorem 1.28. A topological space (X, τ) is a $\delta - R_0$ space if and only if for every x and y in X. $Cl_{\delta}(\{x\}) \neq Cl_{\delta}(\{y\})$ implies $Cl_{\delta}(\{x\})$ I $Cl_{\delta}(\{y\}) = \phi$.

Proof. Necessity. Suppose that (X, τ) is $\delta - R_0$ and $x, y \in X$ such that $Cl_{\delta}(\{x\}) \neq Cl_{\delta}(\{y\})$. Then there exists $z \in Cl_{\delta}(\{x\})$ such that $z \notin Cl_{\delta}(\{y\})$ (or $z \in Cl_{\delta}(\{y\})$ such that $z \notin Cl_{\delta}(\{x\})$. There exists $V \in \tau_{\delta}$ such that $y \notin V$ and $z \in V$; hence $x \in V$. Therefore, we have $x \notin Cl_{\delta}(\{y\})$. Thus $x \in [X - Cl_{\delta}(\{y\})] \in \tau_{\delta},$ which implies $Cl_{\delta}(\{x\}) \subseteq \left[X - Cl_{\delta}(\{y\}) \right]$ and $Cl_{\delta}(\lbrace x \rbrace) \mathbf{I} \ Cl_{\delta}(\lbrace y \rbrace) = \mathbf{\phi}.$ The proof for otherwise is similar.

Sufficiency. Let $V \in \tau_{\delta}$ and let $x \in V$. We will show that $Cl_{\delta}(\{x\}) \subseteq V$. Let $y \notin V$, i.e., $y \in (X - V)$. Then $x \neq y$ and $x \notin Cl_{\delta}(\{y\})$. This shows that $Cl_{\delta}(\{x\}) \neq Cl_{\delta}(\{y\})$. By assumption, $Cl_{\delta}(\{x\}) I Cl_{\delta}(\{y\}) = \phi$. Hence $y \notin Cl_{\delta}(\{x\})$ and therefore $Cl_{\delta}(\{x\}) \subseteq V$.

Theorem 1.29. A topological space (X, τ) is a $\delta - R_0$ space if and only if for any points x and y in X. $Ker_{\delta}(\{x\}) \neq Ker_{\delta}(\{y\})$ implies $Ker_{\delta}(\{x\}) \neq Ker_{\delta}(\{y\})$.

Proof. Suppose that (X, τ) is a $\delta - R_0$ space. Thus by Lemma 1.27, for any points x and y in X if $Ker_{\delta}(\{x\}) \neq Ker_{\delta}(\{y\})$ then $Cl_{\delta}(\{x\}) \neq Cl_{\delta}(\{y\})$. Now we prove that $Ker_{\delta}(\{x\})$ I $Ker_{\delta}(\{y\}) = \phi$. Assume that $z \in Ker_{\delta}(\{x\})$ I $Ker_{\delta}(\{y\})$. By $z \in Ker_{\delta}(\{x\})$ and

Lemma 1.26, it follows that $x \in Ker_{\delta}(\{z\})$. Since $x \in Ker_{\delta}(\{x\}),$ Theorem 1.28, by $Cl_{\delta}(\lbrace x \rbrace) = Cl_{\delta}(\lbrace z \rbrace).$ Similarly, we have $Cl_{\delta}(\lbrace y \rbrace) = Cl_{\delta}(\lbrace z \rbrace) = Cl_{\delta}(\lbrace x \rbrace)$. This is а contradiction. Therefore, we have $Ker_{\delta}(\{x\})$ I $Ker_{\delta}(\{y\}) = \phi$.

Conversely, let (X, τ) be a topological space such that for any points x and y in X, $Ker_{\delta}(\{x\}) \neq Ker_{\delta}(\{y\})$ implies $Ker_{\delta}(\lbrace x \rbrace)$ I $Ker_{\delta}(\lbrace y \rbrace) = \phi$. If $Cl_{\delta}(\lbrace x \rbrace) \neq Cl_{\delta}(\lbrace y \rbrace)$, then by Lemma 1.27, $Ker_{\delta}(\{x\}) \neq Ker_{\delta}(\{y\})$. Hence $Ker_{\delta}(\{x\})$ I $Ker_{\delta}(\{y\}) = \phi$ which implies $Cl_{\delta}(\{x\})$ I $Cl_{\delta}(\{y\}) = \phi$. Because $z \in Ker_{\delta}(\{x\})$ implies $x \in Ker_{\delta}(\{z\}).$ that Therefore $Ker_{\delta}(\{x\})$ I $Ker_{\delta}(\{y\}) \neq \phi$. By hypothesis, we $Ker_{\delta}(\{x\}) = Ker_{\delta}(\{z\}).$ have Then $z \in Cl_{\delta}(\{x\}) I Cl_{\delta}(\{y\})$ implies that $Ker_{\delta}(\{x\}) = Ker_{\delta}(\{z\}) = Ker_{\delta}(\{y\})$. This is a contradiction. Hence, $Cl_{\delta}(\{x\}) I Cl_{\delta}(\{y\}) = \phi$. By Theorem 1.28 (X, τ) is a $\delta - R_0$ space.

Theorem 1.30. For a topological space (X, τ) , the following properties are equivalent:

(1) (X, τ) is a $\delta - R_0$ space;

(2) For any $A \neq \phi$ and $G \in \tau_{\delta}$ such that AI $G \neq \phi$, there exists $F \in C_{\delta}(X, \tau)$ such that AI $F \neq \phi$ and $F \subseteq G$;

(3) Any $G \in \tau_{\delta}$, $G = U\{F \in C_{\delta}(X, \tau) | F \subseteq G\}$;

(4) Any
$$F \in C_{\delta}(X, \tau_{\delta}), F = I \{G \in \tau_{\delta} | F \subseteq G\};$$

(5) For any $x \in X$, $Cl_{\delta}(\{x\}) \subseteq Ker_{\delta}(\{x\})$.

Proof. (1) \Rightarrow (2): Let *A* be a nonempty subset of *X* and $G \in \tau_{\delta}$ such that $AI \ G \neq \phi$. There exists $x \in AI$ G. Since $x \in G \in \tau_{\delta}$, $Cl_{\delta}(\{x\}) \subseteq G$. Set $F = Cl_{\delta}(\{x\})$. Then F is a δ -closed subset of X such that $F \subseteq G$ and AI $F \neq \phi$.

 $(2) \Rightarrow (3): \qquad \text{Let} \qquad G \in \tau_{\delta}. \text{ Then} \\ \cup \{F \in C_{\delta}(X, \tau) | F \subseteq G\} \subseteq G. \text{Let} \quad x \text{ be any point} \\ \text{of } G. \text{ There exists } F \in C_{\delta}(X, \tau) \text{ such that } x \in F \\ \text{and} \qquad F \subseteq G. \qquad \text{Therefore,} \qquad \text{we} \quad \text{have} \\ x \in F \subseteq \cup \{F \in C_{\delta}(X, \tau) | F \subseteq G\} \quad \text{and} \quad \text{hence} \\ G = \cup \{F \in C_{\delta}(X, \tau) | F \subseteq G\}. \end{cases}$

 $(3) \Rightarrow (4)$: This is obvious.

 $(4) \Rightarrow (5): \text{ Let } x \text{ be any point of } X \text{ and}$ $y \notin Ker_{\delta}(\{x\}). \text{ There exists } V \in \tau_{\delta} \text{ such that}$ $x \in V \text{ and } y \notin V; \text{ hence } Cl_{\delta}(\{x\}) \text{ I } V = \phi. \text{ By } (4)$ $(\text{ I } \{G \in \tau_{\delta} | Cl_{\delta}(\{y\}) \subseteq G\}) \text{ I } V = \phi. \text{ There exists}$ $G \in \tau_{\delta} \text{ such that } x \notin G \text{ and } Cl_{\delta}(\{y\}) \subseteq G. \\ \text{ Therefore } Cl_{\delta}(\{x\}) \text{ I } G = \phi \text{ and } y \notin Cl_{\delta}(\{x\}). \\ \text{ Consequently, we obtain } Cl_{\delta}(\{x\}) \subseteq Ker_{\delta}(\{x\}). \end{cases}$

(5) \Rightarrow (1): Let $G \in \tau_{\delta}$ and $x \in G$. Suppose $y \in Ker_{\delta}(\{x\})$. Then $x \in Cl_{\delta}(\{y\})$ and $y \in G$. This implies that $Cl_{\delta}(\{x\}) \subseteq Ker_{\delta}(\{x\}) \subseteq G$. Therefore, (X, τ) is a $\delta - R_0$ space.

Corollary 1.31. For a topological space (X, τ) , the following properties are equivalent:

- $(1)(X, \tau)$ is a δR_0 space;
- (2) $Cl_{\delta}(\{x\}) = Ker_{\delta}(\{x\})$ for all $x \in X$.

Proof. (1) \Rightarrow (2): Suppose that (X, τ) is a $\delta - R_0$ space. By Theorem 1.30, $Cl_{\delta}(\{x\}) \subseteq Ker_{\delta}(\{x\})$ for each $x \in X$. Let $y \in Ker_{\delta}(\{x\})$. Then $x \in Cl_{\delta}(\{y\})$ and so $Cl_{\delta}(\{x\}) = Cl_{\delta}(\{y\})$. Therefore, $y \in Cl_{\delta}(\{x\})$ and

hence $Ker_{\delta}(\{x\}) \subseteq Cl_{\delta}(\{x\})$. This shows that $Cl_{\delta}(\{x\}) = Ker_{\delta}(\{x\})$.

 $(2) \Rightarrow (1)$: This is obvious by Theorem 1.30.

Theorem 1.32. For a topological space (X, τ) , the following properties are equivalent:

(1) (X, τ) is a $\delta - R_0$ space;

(2) $x \in Cl_{\delta}(\{y\})$ if and only if $y \in Cl_{\delta}(\{x\})$, for any points x and y in X.

Proof. (1) \Rightarrow (2): Assume that X is $\delta - R_0$. Let $x \in Cl_{\delta}(\{y\})$ and D be any δ -open set such that $y \in D$. Now by hypothesis, $x \in D$. Therefore, every δ -open set containing y contains x. Hence $y \in Cl_{\delta}(\{x\})$.

(2) \Rightarrow (1): Let U be a δ -open set and $x \in U$. If $y \notin U$, then $x \notin Cl_{\delta}(\{y\})$ and hence $y \notin Cl_{\delta}(\{x\})$. This implies that $Cl_{\delta}(\{x\}) \subseteq U$. Hence (X, τ) is $\delta - R_0$.

Theorem 1.33. For a topological space (X, τ) , the following properties are equivalent:

$$(1)(X, \tau)$$
 is a $\delta - R_0$ space;

(2) If *F* is δ -closed, then $F = Ker_{\delta}(F)$.

(3) If F is δ -closed and $x \in F$, then $Ker_{\delta}(F) \subseteq F$.

(4) If
$$x \in X$$
, then $Ker_{\delta}(\{x\}) \subseteq Cl_{\delta}(\{x\})$.

Proof. (1) \Rightarrow (2): Let *F* be a δ -closed set and $x \notin F$. Thus (X - F) is a δ -open set containing *x*. Since (X, τ) is $\delta - R_0$. $Cl_{\delta}(\{x\}) \subseteq (X - F)$.

Thus $Cl_{\delta}({x})I F = \phi$ and by Lemma 1.24 $x \notin Ker_{\delta}(F)$. Therefore $Ker_{\delta}(F) = F$.

(2) \Rightarrow (3): In general, $A \subseteq B$ implies $Ker_{\delta}(A) \subseteq Cl_{\delta}(B)$. Therefore, it follows from (2) that $Ker_{\delta}(\{x\}) \subseteq Ker_{\delta}(F) = F$.

$$(3) \Rightarrow (4): Since \ x \in Cl_{\delta}(\{x\}) \text{ and } Cl_{\delta}(\{x\}) \text{ is}$$

$$\delta - closed, \text{ by } (3), \ Ker_{\delta}(\{x\}) \subseteq Cl_{\delta}(\{x\}).$$

(4) \Rightarrow (1) We show the implication by using Theorem 3.19. Let $x \in Cl_{\delta}(\{y\})$. Then by Lemma 1.26, $y \in Ker_{\delta}(\{x\})$. Since $x \in Cl_{\delta}(\{x\})$ and $Cl_{\delta}(\{x\})$ is a δ -closed set, by (4) we obtain $y \in Ker_{\delta}(\{x\}) \subseteq Cl_{\delta}(\{x\})$. Therefore $x \in Cl_{\delta}(\{y\})$ implies $y \in Cl_{\delta}(\{x\})$. The converse is obvious and (X, τ) is $\delta - R_{0}$.

Theorem 1.34. Let (X, τ) be a topological space. Then I $\{Cl_{\delta}(\{x\})|x \in X\} = \phi$ if and only if $Ker_{\delta}(\{x\}) \neq X$ for every $x \in X$.

Proof. Necessity. Suppose that I $\{Cl_{\delta}(\{x\})|x \in X\} = \phi$. Assume that there is a point y in X such that $Ker_{\delta}(\{y\}) = X$. Then $y \notin O$, where O is some proper δ -open Χ. that subset of This implies $y \in \mathbf{I} \{ Cl_{\delta}(\{x\}) | x \in X \}.$ But this is а contradiction.

Sufficiency. Assume that $Ker_{\delta}({x}) \neq X$ for every $x \in X$. If there exists a point $y \in X$ such that $y \in I\{Cl_{\delta}({x})|x \in X\}$, then every δ -open set containing y must contain every point of X. This implies that the space X is the unique δ -open set containing y. Hence $Ker_{\delta}(\{x\}) = X$ which is a contradiction. Therefore, I $\{Cl_{\delta}(\{x\}) | x \in X\} = \phi$.

Definition 1.35. A filter base F is called δ -*convergent* to a point x in X, if for any δ -*open* set U of X containing x, there exists B in F such that B is a subset of U.

Lemma 1.36. Let (X, τ) be a topological space and x and y be any two points in X such that every net in X δ -converging to y δ -converges to x. Then $x \in Cl_{\delta}(\{y\})$.

Proof. Suppose that $x_{\alpha} = y$ for $\alpha \in I$. Then $\{x_{\alpha} : \alpha \in I\}$ is a net in $Cl_{\delta}(\{y\})$. Since $\{x_{\alpha} : \alpha \in I\}$ δ -converges to y, so $\{x_{\alpha} : \alpha \in I\}$ δ -converges to x and this implies that $x \in Cl_{\delta}(\{y\})$.

Theorem 1.37. For a topological space (X, τ) , the following statements are equivalent:

(1) (X, τ) is $\delta - R_0$ space;

(2) If $x, y \in X$, then $y \in Cl_{\delta}(\{x\})$ if and only if every net in X δ -converging to y δ -converges to x.

Proof. (1) \Rightarrow (2): Let $x, y \in X$ such that $y \in Cl_{\delta}(\{x\})$. Suppose that $\{x_{\alpha} : \alpha \in I\}$ is a net in X such that this net δ -converges to y. Since $y \in Cl_{\delta}(\{x\})$ so by Theorem 1.28 we have $Cl_{\delta}(\{x\}) = Cl_{\delta}(\{y\})$. Therefore $x \in Cl_{\delta}(\{y\})$. This means that the net $\{x_{\alpha} : \alpha \in I\}$ δ -converges to x.

Conversely, let $x, y \in X$ such that every net in $X \quad \delta$ -converging to $y \quad \delta$ -converges to x. Then $x \in Cl_{\delta}(\{y\})$ by Lemma 1.36. By

Theorem 1.28, we have
$$Cl_{\delta}(\{x\}) = Cl_{\delta}(\{y\})$$
. Therefore $y \in Cl_{\delta}(\{x\})$.

 $(2) \Rightarrow (1)$: Assume that x and y are any two of X points such that $Cl_{\delta}(\{x\}) I Cl_{\delta}(\{y\}) \neq \phi.$ Let $z \in Cl_{\delta}({x}) I Cl_{\delta}({y})$. So there exists a net $\{x_{\alpha}: \alpha \in I\}$ in $Cl_{\delta}(\{x\})$ such that $\{x_{\alpha}: \alpha \in I\} \delta$ – converges to Since Ζ.. $z \in Cl_{\delta}(\{y\})$. So by hypothesis $\{x_{\alpha} : \alpha \in I\}$ δ -converges to y. It follows that $y \in Cl_{\delta}(\{x\}).$ Similarly obtain we $x \in Cl_{\delta}(\{y\}).$ Therefore $Cl_{\delta}(\{x\}) = Cl_{\delta}(\{y\})$ and by Theorem 1.28, (X, τ) is $\delta - R_0$.

2. CHARACTERIZATIONS OF MAPPINGS

The purpose of this part is to explore properties and characterizations of δ -continuous, δ -irresolute, δ -open, δ -closed, pre- δ -open, and pre- δ -closed functions.

2.1. DELTA - CONTINUOUS FUNCTIONS

The purpose of this section is to investigate properties and characterizations of δ -continuous functions.

Definition 2.1. A function $f:(X, \tau) \to (Y, \sigma)$ is said to be δ -continuous if $f^{-1}(V) \in \tau_{\delta}$ for every $V \in \sigma$.

Theorem 2.2. Let $f:(X, \tau) \rightarrow (Y, \sigma)$ be a function. Then the following are equivalent:

- (1) f is δ -continuous;
- (2) The inverse image of each closed set in Y is a δ -closed set in X;

(3)
$$Cl_{\delta}[f^{-1}(V)] \subseteq f^{-1}[Cl(V)],$$
 for every $V \subseteq Y;$

(4) $f[Cl_{\delta}(U)] \subseteq Cl[f(U)]$, for every $U \subseteq X$;

(5) For any point $x \in X$ and any open set *V* of *Y* containing f(x), there exists $U \in \tau_{\delta}$ such that $x \in U$ and $f(U) \subseteq V$;

(6) $Bd_{\delta}[f^{-1}(V)] \subseteq f^{-1}[Bd(V)]$, for every $V \subseteq Y$;

(7)
$$f[D_{\delta}(U)] \subseteq Cl[f(U)]$$
, for every $U \subseteq X$;

(8) $f^{-1}[Int(V)] \subseteq Int_{\delta}[f^{-1}(V)]$, for every $V \subseteq Y$;

Proof. (1) \Rightarrow (2): Let $F \subseteq Y$ be closed. Since f is δ -continuous, $f^{-1}(Y-F) = X - f^{-1}(F)$ is δ -open. Therefore, $f^{-1}(F)$ is δ -closed in X.

(2) \Rightarrow (3): Since Cl(V) is closed for every $V \subseteq Y$, then $f^{-1}[Cl(V)]$ is δ -closed. Therefore $f^{-1}[Cl(V)] = Cl_{\delta}[f^{-1}(Cl(V))] \supseteq Cl_{\delta}[f^{-1}(V)].$

 $(3) \Rightarrow (4): \text{ Let } U \subseteq X \text{ and } f(U) = V. \text{ Then}$ $Cl_{\delta} \left[f^{-1}(V) \right] \subseteq f^{-1} \left[Cl(V) \right]. \text{ Thus}$ $Cl_{\delta}(U) \subseteq Cl_{\delta} \left[f^{-1}(f(U)) \right] \subseteq f^{-1} \left[Cl(f(U)) \right] \text{ and}$ $f \left[Cl_{\delta}(U) \right] \subseteq Cl \left[f(U) \right].$

 $(4) \Rightarrow (2): \text{ Let } W \subseteq Y \text{ be a closed set, and}$ $U = f^{-1}(W). \text{ Then } f \left[Cl_{\delta}(U) \right] \subseteq Cl \left[f(U) \right]$ $= Cl \left[f \left(f^{-1}(W) \right) \right] \subseteq Cl(W) = W. \text{ Thus}$ $Cl_{\delta}(U) \subseteq f^{-1} \left[f \left(Cl_{\delta}(U) \right) \right] \subseteq f^{-1}(W) = U. \text{ So } U \text{ is}$ $\delta - closed.$

 $(2) \Rightarrow (1)$: Let $V \subseteq Y$ be an open set. Then Y - V is closed. Then $f^{-1}(Y - V) = X - f^{-1}(V)$ is δ -closed in X and hence $f^{-1}(V)$ is δ -open in X.

(1) \Rightarrow (5): Let $f:(X, \tau) \rightarrow (Y, \sigma)$ be δ -continuous. For any $x \in X$ and any open set V of Y containing f(x), $U = f^{-1}(V) \in \tau_{\delta}$, and $f(U) = f[f^{-1}(V)] \subseteq V$.

(5) \Rightarrow (1): Let $V \in \sigma$. We prove $f^{-1}(V) \in \tau_{\delta}$. Let $x \in f^{-1}(V)$. Then $f(x) \in V$ and there exists $U \in \tau_{\delta}$ such that $x \in U$ and $f(x) \in f(U) \subseteq V$. Hence $x \in U \subseteq f^{-1}[f(U)] \subseteq f^{-1}(V)$. It shows that $f^{-1}(V)$ is a δ -neighborhood of each of its points. Therefore $f^{-1}(V) \in \tau_{\delta}$.

(6) \Rightarrow (8): Let $V \subseteq Y$. Then by hypothesis, $Bd_{\delta}\left\lceil f^{-1}(V)\right\rceil \subseteq f^{-1}\left\lceil Bd(V)\right\rceil$ $\Rightarrow f^{-1}(V) - Int_{\delta} \left[f^{-1}(V) \right] \subseteq f^{-1} \left[V - Int(V) \right]$ $= f^{-1}(V) - f^{-1} \left[Int(V) \right]$ $\Rightarrow f^{-1} \lceil Int(V) \rceil \subseteq Int_{\delta} \lceil f^{-1}(V) \rceil.$ (8) \Rightarrow (6): Let $V \subseteq Y$. Then by hypothesis, $f^{-1} \lceil Int(V) \rceil \subseteq Int_{\delta} \lceil f^{-1}(V) \rceil$ $f^{-1}(V) - Int_{\delta} [f^{-1}(V)] \subseteq f^{-1}(V) - f^{-1} [Int(V)] = f^{-1} [V - Int(V)]$ $\Rightarrow Bd_{\delta} \lceil f^{-1}(V) \rceil \subseteq f^{-1} \lceil Bd(V) \rceil.$ $(1) \Rightarrow (7):$ It is obvious, since *f* is δ – *continuous* and by (4) $f \left[Cl_{\delta}(U) \right] \subseteq Cl \left[f(U) \right]$ for each $U \subseteq X$. So $f \lceil D_{\delta}(U) \rceil \subseteq Cl \lceil f(U) \rceil.$

 $(7) \Rightarrow (1): \text{Let } U \subseteq Y \text{ be an open set, } V = Y - U$ and $f^{-1}(V) = W$. Then by hypothesis $f[D_{\delta}(W)] \subseteq Cl[f(W)].$ Thus $f\left[D_{\delta}\left(f^{-1}(V)\right)\right] \subseteq Cl\left[f\left(f^{-1}(V)\right)\right] \subseteq Cl(V) = V.$ Then $D_{\delta}\left[f^{-1}(V)\right] \subseteq f^{-1}(V)$ and $f^{-1}(V)$ is δ -closed. Therefore, f is δ -continuous.

(1) \Rightarrow (8): Let $V \subseteq Y$. Then $f^{-1}[Int(V)]$ is δ -open in X. Thus $f^{-1}[Int(V)] =$ $Int_{\delta}[f^{-1}(Int(V))] \subseteq Int_{\delta}[f^{-1}(V)]$. Therefore $f^{-1}[Int(V)] \subseteq Int_{\delta}[f^{-1}(V)]$.

(8) \Rightarrow (1): Let $V \subseteq Y$ be an open set. Then $f^{-1}(V) = f^{-1}[Int(V)] \subseteq Int_{\delta}[f^{-1}(V)]$. Therefore, $f^{-1}(V)$ is δ -open. Hence f is δ -continuous.

In the next Theorem, $\#\delta - c$. denotes the set of points *x* of *X* for which a function $f:(X,\tau) \rightarrow (Y,\sigma)$ is not δ -continuous.

Theorem 2.3. $\#\delta - c$. is identical with the union of the δ -*frontiers* of the inverse images of δ -*open* sets containing f(x).

Proof. Suppose that f is not δ -continuous at a point x of X. Then there exists an open set $V \subseteq Y$ containing f(x) such that f(U)is not a subset of V for every $U \in \tau_s$ containing х. Hence. we have $UI f^{-1}(X - f^{-1}(V)) \neq \phi$ for every $U \in \tau_{s}$ containing *x*. It follows that $x \in Cl_{\delta} [X - f^{-1}(V)].$ We have also $x \in f^{-1}(V) \subseteq Cl_{\delta}[f^{-1}(V)]$. This means that $x \in Fr_{\delta}[f^{-1}(V)]$. Now, let f be δ -continuous at $x \in X$ and $V \subset Y$ any open set containing f(x). Then, $x \in f^{-1}(V)$ is a δ -open set of *X*. Thus. $x \in Int_{\delta} \lceil f^{-1}(V) \rceil$ and therefore $x \notin Fr_{\delta} \left[f^{-1}(V) \right]$ for every open set V containing f(x).

Remarks 2.4. (1) Every δ – *continuous* function is continuous but the converse may not be true.

(2) If a function $f:(X,\tau) \to (Y,\sigma)$ is δ -continuous and a function $g:(Y,\sigma) \to (Z, \vartheta)$ is δ -continuous, then $gof:(X,\tau) \to (Z, \vartheta)$ is δ -continuous.

(3) If a function $f:(X, \tau) \rightarrow (Y, \sigma)$ is δ -continuous and a function $g:(Y, \sigma) \rightarrow (Z, \vartheta)$ is continuous, then $g \circ f:(X, \tau) \rightarrow (Z, \vartheta)$ is δ -continuous.

(4) Let (X, τ) and (Y, σ) be topological spaces. If $f:(X, \tau) \rightarrow (Y, \sigma)$ is a function, and one of the following

(a) $f^{-1}[Int(B)] \subseteq Int_{\delta}[f^{-1}(B)]$ for each $B \subseteq Y$.

(b) $Cl_{\delta}[f^{-1}(B)] \subseteq f^{-1}[Cl(B)]$ for each $B \subseteq Y$.

(c) $f[Cl_{\delta}(A)] \subseteq Cl[f(A)]$ for each $A \subseteq X$ holds, then f is continuous.

Lemma 2.5. Let $A \subseteq Y \subseteq X$, *Y* is δ -open in *X* and *A* is δ -open in *Y*. Then *A* is δ -open in *X*.

Proof. Since *A* is δ -*open* in *Y*, there exists a δ -*open* set $U \subseteq X$ such that A = YIU. Thus *A* being the intersection of two δ -*open* sets in *X*, is δ -*open* in *X*.

Theorem 2.6.Let $f:(X,\tau) \to (Y,\sigma)$ be a mapping and $\{U_i: i \in I\}$ be a cover of X such that $U_i \in \tau_\delta$ for each $i \in I$. Then prove that f is δ -continuous.

Proof. Let $V \subseteq Y$ be an open set, then $(f|U_i)^{-1}(V)$ is δ -open in U_i for each $i \in I$.

Since U_i is δ -open in X for each $i \in I$. So by Lemma 2.5, $(f|U_i)^{-1}(V)$ is δ -open in Xfor each $i \in I$. But, $f^{-1}(V) = U\{(f|U_i)^{-1}(V): i \in I\}$, then $f^{-1}(V) \in \tau_{\delta}$ because τ_{δ} is a topology on X. This implies

that f is δ -continuous.

2.2. DELTA – IRRESOLUTE FUNCTIONS

In this section, the functions to be considered are those for which inverses of δ -*open* sets are δ -*open*. We investigate some properties and characterizations of such functions.

Definition 2.7. Let (X, τ) and (Y, σ) be topological spaces. A function $f:(X, \tau) \rightarrow (Y, \sigma)$ is called δ -*irresolute* if the inverse image of each δ -*open* set of Y is a δ -*open* set in X.

Theorem 2.8. Let $f: (X, \tau) \rightarrow (Y, \sigma)$ be a function between topological spaces. Then the following are equivalent:

(1) f is δ -irresolute;

(2) the inverse image of each δ -closed set in *Y* is a δ -closed set in *X*;

(3)
$$Cl_{\delta}[f^{-1}(V)] \subseteq f^{-1}[Cl_{\delta}(V)]$$
 for every $V \subseteq Y$;

(4)
$$f[Cl_{\delta}(U)] \subseteq Cl_{\delta}[f(U)]$$
 for every $U \subseteq X$;

(5) $f^{-1}[Int_{\delta}(B)] \subseteq Int_{\delta}[f^{-1}(B)]$ for every $B \subseteq Y$.

Theorem 2.9. Prove that a function $f:(X,\tau) \rightarrow (Y,\sigma)$ is δ -*irresolute* if and only if for each point p in X and each δ -*open* set B in Y with $f(p) \in B$, there is a δ -*open* set A in X such that $p \in A$, $f(A) \subseteq B$.

Proof. Necessity. Let $p \in X$ and $B \in \sigma_{\delta}$ such that $f(p) \in B$. Let $A = f^{-1}(B)$. Since f is δ -*irresolute*, A is δ -*open* in X. Also $p \in f^{-1}(B) = A$ as $f(p) \in B$. Thus we have $f(A) = f \lceil f^{-1}(B) \rceil \subseteq B$.

Sufficiency. Let $B \in \sigma_{\delta}$, let $A = f^{-1}(B)$. We show that A is δ -open in X. For this let $x \in A$. It implies that $f(x) \in B$. Then by hypothesis, there exists $A_x \in \tau_{\delta}$ such that $x \in A_x$ and $f(A_x) \subseteq B$. Then $A_x \subseteq f^{-1}[f(A_x)] \subseteq f^{-1}(B) = A$. Thus $A = U\{A_x : x \in A\}$. It follows that A is δ -open in X. Hence f is δ -irresolute.

Definition 2.10. Let (X, τ) be a topological space. Let $x \in X$ and $N \subseteq X$. We say that N is a δ -*neighborhood* of x if there exists a δ -*open* set M of X such that $x \in M \subseteq N$.

Theorem 2.11. Prove that a function $f:(X,\tau) \rightarrow (Y,\sigma)$ is δ -*irresolute* if and only if for each x in X, the inverse image of every δ -*neighborhood* of f(x), is a δ -*neighborhood* of x.

Proof. Necessity. Let $x \in X$ and let B be a δ -neighborhood of f(x). Then there exists $U \in \sigma_{\delta}$ such that $f(x) \in U \subseteq B$. This implies that $x \in f^{-1}(U) \subseteq f^{-1}(B)$. Since f is δ -irresolute, so $f^{-1}(U) \in \tau_{\delta}$. Hence $f^{-1}(B)$ is a δ -neighborhood of x.

Sufficiency. Let $B \in \sigma_{\delta}$. Put $A = f^{-1}(B)$. Let $x \in A$. Then $f(x) \in B$. But then, B being δ -open set, is a δ -neighborhood of f(x). So by hypothesis, $A = f^{-1}(B)$ is a δ -neighborhood of x. Hence by definition, there exists $A_x \in \tau_{\delta}$ such that $x \in A_x \subseteq A$. Thus $A = U\{A_x : x \in A\}$. It follows that A is a δ -open set in X. Therefore f is δ -irresolute.

Theorem 2.12. Prove that a function $f:(X,\tau) \rightarrow (Y,\sigma)$ is δ -*irresolute* if and only if for each x in X. and each δ -*neighborhood* U of f(x), there is a δ -*neighborhood* V of x such that $f(V) \subseteq U$.

Proof. Necessity. Let $x \in X$ and let U be a δ -neighborhood of f(x). Then there exists $O_{f(x)} \in \sigma_{\delta}$ such that $f(x) \in O_{f(x)} \subseteq U$. It follows that $x \in f^{-1}[O_{f(x)}] \subseteq f^{-1}(U)$. By hypothesis, $f^{-1}[O_{f(x)}] \in \tau_{\delta}$. Let $V = f^{-1}(U)$. Then it follows that V is a δ -neighborhood of x and $f(V) = f[f^{-1}(U)] \subseteq U$.

Sufficiency. Let $B \in \sigma_{\delta}$. Put $O = f^{-1}(B)$. Let $x \in O$. Then $f(x) \in B$. Thus B is a δ -neighborhood of f(x). So by hypothesis, there exists a δ -neighborhood V_x of x such that $f(V_x) \subseteq B$. Thus it follows that $x \in V_x \subseteq f^{-1}[f(V_x)] \subseteq f^{-1}(B) = O$. Since V_x is a δ -neighborhood of x, so there exists an $O_x \in \tau_{\delta}$ such that $x \in O_x \subseteq V_x$. Hence $x \in O_x \subseteq O$, $O_x \in \tau_{\delta}$. Thus $O = \bigcup\{O_x : x \in O\}$. It follows that O is δ -open in X. Therefore, f is δ -irresolute.

Theorem 2.13. Prove that a function $f:(X,\tau) \to (Y,\sigma)$ is δ -*irresolute* if and only if $f[D_{\delta}(A)] \subseteq f(A) U D_{\delta}[f(A)]$, for all $A \subseteq X$.

Proof. Necessity. Let $f:(X,\tau) \to (Y,\sigma)$ be δ -*irresolute.* Let $A \subseteq X$, and $a_0 \in D_{\delta}(A)$. Assume that $f(a_0) \notin f(A)$ and let V denote a δ -*neighborhood* of $f(a_0)$. Since f is δ -*irresolute*, so by Theorem 2.12, there exists a δ -*neighborhood* U of a_0 such that $f(U) \subseteq V$. From $a_0 \in D_{\delta}(A)$, it follows that $U \text{ I } A \neq \phi$; there exists, therefore, at least one element $a \in U \text{ I } A$ such that $f(a) \in f(A)$ and $f(a) \in f(V)$. Since $f(a_0) \notin f(A)$, we have $f(a) \neq f(a_0)$. Thus every δ -neighborhood of $f(a_0)$ contains an element of f(A) different from $f(a_0)$, consequently, $f(a_0) \in D_{\delta}[f(A)]$. This proves necessity of the condition.

Sufficiency. Assume that f is not δ -*irresolute*. Then by Theorem 2.12, there exists $a_0 \in X$ and a δ -*neighborhood* V of $f(a_0)$ such that every δ -*neighborhood* U of a_0 contains at least one element $a \in U$ for which $f(a) \notin V$. Put $A = \{a \in X : f(a) \notin V\}$. Then $a_0 \notin A$ since $f(a_0) \in V$, and therefore $f(a_0) \notin A$; also $f(a_0) \notin D_{\delta}[f(A)]$ since $VI(V - \{f(a_0)\}) = \phi$. It follows that

 $f(a_0) \in f[D_{\delta}(A)] - [f(A)UD_{\delta}(f(A))] \neq \phi$, which is a contradiction to the given condition.

The condition of the Theorem is therefore sufficient and the theorem is proved.

Theorem 2.14. Let $f:(X,\tau) \to (Y,\sigma)$ be a oneto-one function. Then f is δ -*irresolute* if and only if $f[D_{\delta}(A)] \subseteq D_{\delta}[f(A)]$, for all $A \subseteq X$.

Proof. Necessity. Let f be δ -*irresolute.* Let $A \subseteq X$, $a_0 \in D_{\delta}(A)$ and V be a δ -*neighborhood* of $f(a_0)$. Since f is δ -*irresolute*, so by Theorem 2.12, there exists a δ -*neighborhood* U of a_0 such that $f(U) \subseteq V$. But $a_0 \in D_{\delta}(A)$; hence there exists an element $a \in UI A$ such that $a \neq a_0$; then $f(a) \in f(A)$ and, since f is one to one, $f(a) \neq f(a_0)$. Thus every δ -*neighborhood* V of $f(a_0)$ contains an element of f(A) different from $f(a_0)$; consequently $f(a_0) \in D_{\delta}[f(A)]$. We have therefore $f[D_{\delta}(A)] \subseteq D_{\delta}[f(A)]$.

Sufficiency. Follows from Theorem 2.13.

2.3. DELTA - OPEN FUNCTIONS

The purpose of this section is to investigate some characterizations of δ -*open* mappings.

Definition 2.15. Let (X, τ) and (Y, σ) be topological spaces. A function $f:(X, \tau) \rightarrow (Y, \sigma)$ is called δ -open if for every open set G in X, f(G) is a δ -open set in Y.

Theorem 2.16. Prove that a mapping

 $f:(X,\tau) \to (Y,\sigma)$ is δ -open if and only if for each $x \in X$, and $U \in \tau$ such that $x \in U$, there exists a δ -open set $W \subseteq Y$ containing f(x)such that $W \subseteq f(U)$.

Proof. Follows immediately from Definition 2.15.

Theorem 2.17. Let $f:(X, \tau) \to (Y, \sigma)$ be δ -open. If $W \subseteq Y$ and $F \subseteq X$ is a closed set containing $f^{-1}(W)$, then there exists a δ -closed $H \subseteq Y$ containing W such that $f^{-1}(H) \subseteq F$.

Proof. Let H = Y - f(Y - F). Since $f^{-1}(W) \subseteq F$, we have $f^{-1}(Y - F) \subseteq (Y - W)$. Since f is δ -open, then H is δ -closed and $f^{-1}(H) = X - f^{-1}[f(X - F)] \subseteq X - (X - F) = F$.

Theorem 2.18. Let $f:(X, \tau) \to (Y, \sigma)$ be a δ -open function and let $B \subseteq Y$. Then $f^{-1} \Big[Cl_{\delta} \Big(Int_{\delta} \big(Cl_{\delta} \big(B \big) \big) \Big] \subseteq Cl \Big[f^{-1} \big(B \big) \Big].$

Proof. $Cl[f^{-1}(B)]$ is closed in X containing $f^{-1}(B)$. By Theorem 2.17, there exists a δ -closed set $B \subseteq H \subseteq Y$ such that $f^{-1}(H) \subseteq Cl[f^{-1}(B)]$. Thus, $f^{-1}\Big[Cl_{\delta}\big(Int_{\delta}\big(Cl_{\delta}(B)\big)\big)\Big] \subseteq f^{-1}\Big[Cl_{\delta}\big(Int_{\delta}\big(Cl_{\delta}(H)\big)\big)\Big]$ $\subseteq f^{-1}\Big[H\Big] \subseteq Cl\Big[f^{-1}(B)\Big].$

Theorem 2.19. Prove that a function $f:(X, \tau) \longrightarrow (Y, \sigma)$ is δ -open if and only if $f[Int(A)] \subseteq Int_{\delta}[f(A)]$, for all $A \subseteq X$.

Proof.Necessity. Let $A \subseteq X$. Let $x \in Int(A)$. Then there exists $U_x \in \tau$ such that $x \in U_x \subseteq A$. So $f(x) \in f(U_x) \subseteq f(A)$. and by hypothesis, $f(U_x) \in \sigma_{\delta}$. Hence $f(x) \in Int_{\delta}[f(A)]$. Thus $f[Int(A)] \subseteq Int_{\delta}[f(A)]$.

Sufficiency. Let $U \in \tau$. Then by hypothesis, $f[Int(U)] \subseteq Int_{\delta}[f(U)]$. Since Int(U) = U as U is open. Also $Int_{\delta}[f(U)] \subseteq f(U)$. Hence $f(U) = Int_{\delta}[f(U)]$. Thus f(U) is δ -open open in Y. So f is δ -open.

Remark 2.20. The equality may not hold in the preceding Theorem.

Theorem 2.21. Prove that a function $f:(X,\tau) \rightarrow (Y,\sigma)$ is δ -open if and only if $Int[f^{-1}(B)] \subseteq f^{-1}[Int_{\delta}(B)]$, for all $B \subseteq Y$.

Proof. Necessity. Let $B \subseteq Y$. Since $Int[f^{-1}(B)]$ is open in X and f is δ -open, $f[Int(f^{-1}(B))]$ is δ -open in Y. Also we have $f[Int(f^{-1}(B))] \subseteq f[f^{-1}(B)] \subseteq B$. Hence, $f[Int(f^{-1}(B))] \subseteq Int_{\delta}(B)$. Therefore $Int(f^{-1}(B)) \subseteq f^{-1}[Int_{\delta}(B)]$. **Sufficiency.** Let $A \subseteq X$. Then $f(A) \subseteq Y$. Hence by hypothesis, we obtain $Int(A) \subseteq Int[f^{-1}(f(A))] \subseteq f^{-1}[Int_{\delta}(f(A))]$. Thus $f[int(A)] \subseteq Int_{\delta}[f(A)]$, for all $A \subseteq X$. Hence, by Theorem 2.19, f is δ -open.

Theorem 2.22. Let $f:(X,\tau) \to (Y,\sigma)$ be a mapping. Then a necessary and sufficient condition for f to be δ -open is that $f^{-1}[Cl_{\delta}(B)] \subseteq Cl[f^{-1}(B)]$ for every subset B of Y.

Proof. Necessity. Assume f is δ -open. Let $B \subseteq Y$. Let $x \in f^{-1}[Cl_{\delta}(B)]$. Then $f(x) \in Cl_{\delta}(B)$. Let $U \in \tau$ such that $x \in U$. Since f is δ -open, then f(U) is a δ -open set in Y. Therefore, $BI \ f(U) \neq \phi$. Then $UI \ f^{-1}(B) \neq \phi$. Hence $x \in Cl[f^{-1}(B)]$. We conclude that $f^{-1}[Cl_{\delta}(B)] \subseteq Cl[f^{-1}(B)]$.

Sufficiency. Let $B \subseteq Y$. Then $(Y-B) \subseteq Y$. By hypothesis, $f^{-1} [Cl_{\delta}(Y-B)] \subseteq Cl [f^{-1}(Y-B)]$. This implies that $X - Cl [f^{-1}(Y-B)] \subseteq X - f^{-1} [Cl_{\delta}(Y-B)]$. Hence $X - Cl [X - f^{-1}(B)] \subseteq f^{-1} [Y - Cl_{\delta}(Y-B)]$. By applying Theorem 10[18], $Int [f^{-1}(B)] \subseteq f^{-1} [Int_{\delta}(B)]$. Now form Theorem 2.21, it follows that f is δ -open.

2.4. DELTA - CLOSED FUNCTIONS

In this section we introduce δ -*closed* functions and study certain properties and characterizations of this type of functions.

Definition 2.23. A mapping $f:(X, \tau) \rightarrow (Y, \sigma)$ is called δ -*closed* if the image of each closed set in X is a δ -*closed* set in Y.

Theorem 2.24. Prove that a mapping $f:(X,\tau) \to (Y,\sigma)$ is δ -*closed* if and only if $Cl_{\delta}[f(A)] \subseteq f[Cl(A)]$ for each $A \subseteq X$.

Proof. Necessity. Let f be δ -closed and let $A \subseteq X$. Then $f(A) \subseteq f[Cl(A)]$ and f[Cl(A)] is a δ -closed set in Y. Thus $Cl_{\delta}[f(A)] \subseteq f[Cl(A)]$.

Sufficiency. Suppose that $Cl_{\delta}[f(A)] \subseteq f[Cl(A)]$, for each $A \subseteq X$. Let $A \subseteq X$ be a closed set. Then $Cl_{\delta}[f(A)] \subseteq f[Cl(A)] = f(A)$. This shows that f(A) is a δ -closed set. Hence f is δ -closed.

Theorem 2.25. Let $f:(X,\tau) \to (Y,\sigma)$ be δ -*closed.* If $V \subseteq Y$ and $E \subseteq X$ is an open set containing $f^{-1}(V)$, then there exists a δ -*open* set $G \subseteq Y$ containing V such that $f^{-1}(G) \subseteq E$.

Proof. Let G = Y - f(X - E). Since $f^{-1}(V) \subseteq E$, we have $f(X - E) \subseteq Y - V$. Since f is δ -closed, then G is a δ -open set and $f^{-1}(G) = X - f^{-1} [f(X - E)] \subseteq X - (X - E) = E$.

Theorem 2.26. Suppose that $f:(X, \tau) \to (Y, \sigma)$ is a δ -closed mapping. Then $Int_{\delta} [Cl_{\delta}(f(A))] \subseteq f [Cl(A)]$ for every subset A of X.

Proof. Suppose f is a δ -closed mapping and A is an arbitrary subset of X. Then f[Cl(A)] is δ -closed in Y. Then $Int_{\delta}[Cl_{\delta}(f(Cl(A)))] \subseteq f[Cl(A)]$. But also $Int_{\delta}[Cl_{\delta}(f(A))] \subseteq Int_{\delta}[Cl_{\delta}(f(Cl(A)))]$. Hence $Int_{\delta}[Cl_{\delta}(f(A))] \subseteq f[Cl(A)]$.

Theorem 2.27. Let $f:(X, \tau) \rightarrow (Y, \sigma)$ be a δ -*closed* function, and $B, C \subseteq Y$.

Proof. (1) If U is an open neighborhood of $f^{-1}(B)$, then there exists a δ -open neighborhood V of B such that $f^{-1}(B) \subseteq f^{-1}(V) \subseteq U$.

(2) If f is also onto, then if $f^{-1}(B)$ and $f^{-1}(C)$ have disjoint open neighborhoods, so have B and C.

Proof. (1) Let V = Y - f(X - U). Then $V^c = Y - V = f(U^c)$. Since f is δ -closed, so Vis a δ -open set. Since $f^{-1}(B) \subseteq U$, we have $V^c = f(U^c) \subseteq f[f^{-1}(B^c)] \subseteq B^c$. Hence, $B \subseteq V$, and thus V is a δ -open neighborhood of B. Further $U^c \subseteq f^{-1}[f(U^c)] = f^{-1}(V^c) = [f^{-1}(V)]^c$. This proves that $f^{-1}(V) \subseteq U$.

(2) If $f^{-1}(B)$ and $f^{-1}(C)$ have disjoint open neighborhoods M and N, then by (1), we have δ -open neighborhoods U and V of B and Crespectively such that $f^{-1}(B) \subseteq f^{-1}(U) \subseteq Int_{\delta}(M)$ and

 $f^{-1}(C) \subseteq f^{-1}(V) \subseteq Int_{\delta}(N)$. Since M and N are disjoint, so are $Int_{\delta}(M)$ and $Int_{\delta}(N)$, hence so $f^{-1}(U)$ and $f^{-1}(V)$ are disjoint as well. It follows that U and V are disjoint too as f is onto.

Theorem 2.28. Prove that a surjective mapping $f:(X,\tau) \rightarrow (Y,\sigma)$ is δ -*closed*, if and only if for each subset *B* of *Y* and each open set *U* in *X* containing $f^{-1}(B)$, there exists a δ -*open* set *V* in *Y* containing *B* such that $f^{-1}(V) \subseteq U$.

Proof. Necessity. This follows from (1) of Theorem 2.27.

Sufficiency. Suppose *F* is an arbitrary closed set in *X*. Let *y* be an arbitrary point in Y - f(F). Then $f^{-1}(y) \subseteq X - f^{-1}[f(F)] \subseteq (X - F)$ and (X - F)

is open in X. Hence by hypothesis, there exists a δ -open set V_y containing y such that $f^{-1}(V_y) \subseteq (X - F)$. This implies that $y \in V_y \subseteq [Y - f(F)]$. Thus $Y - f(F) = U\{V_y : y \in Y - f(F)\}$. Hence Y - f(F), being a union of δ -open sets, is δ -open. Thus its complement f(F) is δ -closed. This shows that f is δ -closed.

Theorem 2.29. Let $f:(X, \tau) \rightarrow (Y, \sigma)$ be a bijection. Then the following are equivalent:

- (a) f is δ -closed.
- (b) f is δ -open.
- (c) f^{-1} is δ -continuous.

Proof. (a) \Rightarrow (b): Let $U \in \tau$. Then X - U is closed in X. By (a), f(X - U) is δ -closed in Y. But f(X - U) = f(X) - f(U) = Y - f(U). Thus f(U) is δ -open in Y. This shows that f is δ -open.

(b) \Rightarrow (c): Let $U \subseteq X$. be an open set. Since fis δ -open. So $f(U) = (f^{-1})^{-1}(U)$ is δ -open in *Y*. Hence f^{-1} is δ -continuous.

(c) \Rightarrow (a): Let A be an arbitrary closed set in X. Then X-A is open in X. Since f^{-1} is δ -continuous, $(f^{-1})^{-1}(X-A)$ is δ -open in Y. But $(f^{-1})^{-1}(X-A) = f(X-A) = Y - f(A)$. Thus f(A) is δ -closed in Y. This shows that f is δ -closed.

Remark 2.30. A bijection $f:(X,\tau) \rightarrow (Y,\sigma)$ may be open and closed but neither δ -open nor δ -closed.

2.5. PRE-DELTA-OPEN FUNCTIONS

The purpose of this section is to introduce and discuss certain properties and characterizations of *pre* $-\delta$ -*open* functions.

Definition 2.31. Let (X, τ) and (Y, σ) be topological spaces. Then a function $f:(X, \tau) \rightarrow (Y, \sigma)$ is said to be $pre-\delta-open$ if and only if for each $A \in \tau_{\delta}$, $f(A) \in \sigma_{\delta}$.

Theorem 2.32. Let $f:(X,\tau) \to (Y,\sigma)$ and $g:(Y,\sigma) \to (Z,\mu)$ be any two $pre-\delta$ -open functions. Then the composition function $gof:(X,\tau) \to (Z,\mu)$ is a $pre-\delta$ -open function.

Proof. Let $U \in \tau_{\delta}$. Then $f(U) \in \sigma_{\delta}$. Since f is $pre-\delta$ -open. But then $g(f(U)) \in \mu_{\delta}$ as g is $pre-\delta$ -open. Hence, gof is $pre-\delta$ -open.

Theorem 2.33. Prove that a mapping $f:(X,\tau) \rightarrow (Y,\sigma)$ is $pre-\delta-open$ if and only if for each $x \in X$ and for any $U \in \tau_{\delta}$ such that $x \in U$, there exists $V \in \sigma_{\delta}$ such that $f(x) \in V$ and $V \subseteq f(U)$.

Proof. Routine.

Theorem 2.34. Prove that a mapping $f:(X,\tau) \rightarrow (Y,\sigma)$ is $pre-\delta$ -open if and only if for each $x \in X$ and for any δ -neighborhood U of x in X, there exists a δ -neighborhood V of f(x) in Y such that $V \subseteq f(U)$.

Proof. Necessity. Let $x \in X$ and let U be a δ – neighborhood x. Then there exists of $W \in \tau_{\delta}$ such that $x \in W \subseteq U$. Then $f(x) \in f(W) \subseteq f(U)$. But $f(W) \in \sigma_{\delta}$ as f is V = f(W) $pre-\delta-open$. Hence is а δ -neighborhood of f(x) and $V \subseteq f(U)$.

Sufficiency. Let $U \in \tau_{\delta}$. Let $x \in U$. Then U is a δ -*neighborhood* of x. So by hypothesis, there exists a δ -*neighborhood* $V_{f(x)}$ of f(x) such that $f(x) \in V_{f(x)} \subseteq f(U)$. It follows at once that

f(U) is a δ -neighborhood of each of its points. Therefore f(U) is δ -open. Hence f is pre- δ -open.

Theorem 2.35. Prove that a function $f:(X, \tau) \rightarrow (Y, \sigma)$ is $pre-\delta-open$ if and only if $f[Int_{\delta}(A)] \subseteq Int_{\delta}[f(A)]$, for all $A \subseteq X$.

Proof. Necessity. Let $A \subseteq X$. Let $x \in Int_{\delta}(A)$. Then there exists $U_x \in \tau_{\delta}$ such that $x \in U_x \subseteq A$. So $f(x) \in f(U_x) \subseteq f(A)$ and by hypothesis, $f(U_x) \in \sigma_{\delta}$. Hence $f(x) \in Int_{\delta}[f(A)]$. Thus $f[Int_{\delta}(A)] \subseteq Int_{\delta}[f(A)]$.

Sufficiency. Let $U \in \tau_{\delta}$. Then by hypothesis, $f[Int_{\delta}(U)] \subseteq Int_{\delta}[f(U)]$. Since $Int_{\delta}(U) = U$ as U is δ -open. Also $Int_{\delta}[f(U)] \subseteq f(U)$. Hence $f(U) = Int_{\delta}[f(U)]$. Thus f(U) is δ -open in Y. So f is $pre-\delta$ -open.

We remark that the equality does not hold in Theorem 2.35 as the following example shows.

Example 2.36. Let $X = Y = \{1, 2\}$. suppose X is antidiscrete and Y is discrete. Let f = Id., $A = \{1\}$. Then $\phi = f [Int_{\delta}(A)] \neq Int_{\delta} [f(A)] = \{1\}$.

Theorem 2.37. Prove that a function $f:(X,\tau) \to (Y,\sigma)$ is $pre-\delta-open$ if and only if $Int_{\delta}[f^{-1}(B)] \subseteq f^{-1}[Int_{\delta}(B)]$, for all $B \subseteq Y$.

Proof. Necessity. Let $B \subseteq Y$. Since $Int_{\delta} [f^{-1}(B)]$ is δ -open in X and f is $pre-\delta$ -open, $f [Int_{\delta} (f^{-1}(B))]$ is δ -open in Y. Also we have $f [Int_{\delta} (f^{-1}(B))] \subseteq f [f^{-1}(B)]$ $\subseteq B$. Hence, $f [Int_{\delta} (f^{-1}(B))] \subseteq Int_{\delta}(B)$. Therefore $Int_{\delta} [f^{-1}(B)] \subseteq f^{-1} [Int_{\delta}(B)]$.

Sufficiency. Let $A \subseteq X$. Then $f(A) \subseteq Y$. Hence by hypothesis, we obtain $Int_{\delta}(A) \subseteq Int_{\delta} [f^{-1}(f(A))] \subseteq f^{-1} [Int_{\delta}(f(A))].$ This implies that $f[Int_{\delta}(A)] \subseteq f[f^{-1}(Int_{\delta}(f(A)))] \subseteq Int_{\delta}[f(A)].$ Thus $f[Int_{\delta}(A)] \subseteq Int_{\delta}[f(A)]$, for all $A \subseteq X$. Hence, by Theorem 2.35, f is $pre-\delta-open$.

Theorem 2.38. Prove that a mapping $f:(X,\tau) \to (Y,\sigma)$ is $pre-\delta-open$ if and only if $f^{-1}[Cl_{\delta}(B)] \subseteq Cl_{\delta}[f^{-1}(B)]$, for every subset *B* of *Y*.

Proof. Necessity. Let $B \subseteq Y$. Let $x \in f^{-1}[Cl_{\delta}(B)].$ Then $f(x) \in Cl_{\delta}(B)$. Let $U \in \tau_{\delta}$ such that $x \in U$. By hypothesis, $f(U) \in \sigma_{\delta}$ and $f(x) \in f(U).$ Thus f(U)I $B \neq \phi$. Hence UI $f^{-1}(B) \neq \phi$. Therefore, $x \in Cl_{\delta}[f^{-1}(B)],$ So we obtain $f^{-1} \left[Cl_{\delta}(B) \right] \subseteq Cl_{\delta} \left[f^{-1}(B) \right].$

Sufficiency. Let $B \subseteq Y$. Then $(Y-B) \subseteq Y$. By hypothesis, $f^{-1} [Cl_{\delta}(Y-B)] \subseteq Cl_{\delta} [f^{-1}(Y-B)]$. This implies that $X - Cl_{\delta} [f^{-1}(Y-B)] \subseteq X - f^{-1} [Cl_{\delta}(Y-B)]$. Hence $X - Cl_{\delta} [X - f^{-1}(B)] \subseteq f^{-1} [Y - Cl_{\delta}(Y-B)]$. By

Theorem 2.7(6)[20],

 $Int_{\delta}[f^{-1}(B)] \subseteq f^{-1}[Int_{\delta}(B)].$ Now by Theorem 2.37, it follows that f is $pre-\delta-open$.

Theorem 2.39. Let $f:(X,\tau) \to (Y,\sigma)$ and $g:(Y,\sigma) \to (Z,\mu)$ be two mappings such that $gof:(X,\tau) \to (Z,\mu)$ is δ -*irresolute*. Then

(1) If g is a $pre-\delta-open$ injection, then f is $\delta-irresolute$.

(2) If f is a pre- δ -open surjection, then g is δ -irresolute.

Proof. (1) Let $U \in \sigma_{\delta}$. Then $g(U) \in \mu_{\delta}$ since g is $pre-\delta$ -open. Also gof is δ -irresolute. Therefore, we have $(gof)^{-1}[g(U)] \in \tau_{\delta}$. Since g is an injection, so we have : $(gof)^{-1}[g(U)] = (f^{-1}og^{-1})[g(U)] =$ $f^{-1}[g^{-1}(g(U))] = f^{-1}(U)$. Consequently $f^{-1}(U)$ is δ -open in X. This proves that f is δ -irresolute.

(2) Let $V \in \mu_{\delta}$. Then $(g \circ f)^{-1}(V) \in \tau_{\delta}$ since $g \circ f$ is δ -irresolute. Also f is $pre-\delta$ -open, $f\left[(g \circ f)^{-1}(V)\right]$ is δ -open in Y. Since f is surjective, we note that $f\left[(g \circ f)^{-1}(V)\right] = [f \circ (g \circ f)^{-1}](V) = [f \circ (f^{-1} \circ g^{-1})](V) = [(f \circ f^{-1}) \circ g^{-1}(V)] = g^{-1}(V)$. Hence g is δ -irresolute.

2.6. PRE-DELTA-CLOSED FUNCTIONS

In this last section, we introduce and explore several properties and characterizations of $pre-\delta-closed$ functions.

Definition 2.40. A function $f:(X, \tau) \rightarrow (Y, \sigma)$ is said to be *pre*- δ -*closed* if and only if the image set f(A) is δ -*closed* for each δ -*closed* subset A of X.

Theorem 2.41. The composition of two $pre-\delta-closed$ mappings is a $pre-\delta-closed$ mapping.

Proof. The straight forward proof is omitted.

Theorem 2.42. Prove that a mapping $f:(X,\tau) \to (Y,\sigma)$ is $pre-\delta$ -closed if and only if $Cl_{\delta}[f(A)] \subseteq f[Cl_{\delta}(A)]$ for every subset A of X.

Proof. Necessity. Suppose f is a $pre-\delta-closed$ mapping and A is an arbitrary subset of X. Then $f[Cl_{\delta}(A)]$ is $\delta-closed$ in Y. Since $f(A) \subseteq f[Cl_{\delta}(A)]$, we obtain $Cl_{\delta}[f(A)] \subseteq f[Cl_{\delta}(A)]$.

Sufficiency. Suppose *F* is an arbitrary δ -closed set in *X*. By hypothesis, we obtain $f(F) \subseteq Cl_{\delta}[f(F)] \subseteq f[Cl_{\delta}(F)] = f(F)$. Hence $f(F) = Cl_{\delta}[f(F)]$. Thus f(F) is δ -closed in *Y*. It follows that *f* is $pre-\delta$ -closed.

Theorem 2.43. Let $f:(X,\tau) \to (Y,\sigma)$ be a *pre*- δ -*closed* function, and $B,C \subseteq Y$.

(1) If U is a δ -open neighborhood of $f^{-1}(B)$, then there exists a δ -open neighborhood V of B such that $f^{-1}(B) \subseteq f^{-1}(V) \subseteq U$.

(2) If f is also onto, then if $f^{-1}(B)$ and $f^{-1}(C)$ have disjoint δ -open neighborhoods, so have B and C.

Proof. (1) Let V = Y - f(X - U). Then $V^{c} = Y - V = f(U^{c})$. Since f is $pre - \delta$ -closed, so V is δ -open. Since $f^{-1}(B) \subseteq U$, we have $V^{c} = f(U^{c}) \subseteq f[f^{-1}(B^{c})] \subseteq B^{c}$. Hence, $B \subseteq V$, and thus V is a δ -open neighborhood of B. Further

 $U^{c} \subseteq f^{-1} \Big[f \Big(U^{c} \Big) \Big] = f^{-1} \Big(V^{c} \Big) = \Big[f^{-1} \big(V \big) \Big]^{c}.$ This proves that $f^{-1} \big(V \big) \subseteq U.$

(2) If $f^{-1}(B)$ and $f^{-1}(C)$ have disjoint δ -open neighborhoods M and N, then by (1), we have δ -open neighborhoods U and V of B and C respectively such that $f^{-1}(B) \subseteq f^{-1}(U) \subseteq Int_{\delta}(M)$ and $f^{-1}(C) \subseteq f^{-1}(V) \subseteq Int_{\delta}(N)$. Since M and N are disjoint, so are $Int_{\delta}(M)$ and $Int_{\delta}(N)$, and hence so $f^{-1}(U)$ and $f^{-1}(V)$ are disjoint as well. It follows that U and V are disjoint too as f is onto.

Theorem 2.44. Prove that a surjective mapping $f:(X, \tau) \longrightarrow (Y, \sigma)$ is

 $pre-\delta-closed$ if and only if for each subset B of Y and each $\delta-open$ set U in X containing $f^{-1}(B)$, there exists a $\delta-open$ set V in Y containing B such that $f^{-1}(V) \subseteq U$.

Proof.Necessity. This follows from (1) of Theorem 2.43.

Sufficiency. Suppose *F* is an arbitrary δ -closed set in X. Let y be an arbitrary Y - f(F). point in Then $f^{-1}(y) \subseteq X - f^{-1} \lceil f(F) \rceil \subseteq (X - F)$ and (X-F) is δ -open in X. Hence by hypothesis, there exists a δ -open set V_{y} containing y such that $f^{-1}(V_y) \subseteq (X - F)$. This implies that $y \in V_y \subseteq [Y - f(F)]$. Thus $Y - f(F) = \mathrm{U}\{V_{y} \mid y \in Y - f(F)\}.$ Hence Y - f(F), being a union of δ -open sets is δ -open. Thus its complement f(F) is δ -*closed*. This shows that f is δ -*closed*.

Theorem 2.45. Let $f:(X, \tau) \longrightarrow (Y, \sigma)$ be a bijection. Then the following are equivalent:

- (1) f is $pre-\delta-closed$.
- (2) f is pre- δ -open.
- (3) f^{-1} is δ -irresolute.

Proof. (1) \Rightarrow (2): Let $U \in \tau_{\delta}$. Then X - Uis δ -closed in X. By (1), f(X - U) is δ -closed in Y. But f(X - U) = f(X) - f(U) = Y - f(U). Thus f(U) is δ -open in Y. This shows that f is $pre - \delta$ -open. $(2) \Rightarrow (3): \text{Let} \quad A \subseteq X. \text{ Since } f \text{ is}$ $pre - \delta - open, \text{ so by Theorem 2.38,}$ $f^{-1} \Big[Cl_{\delta} \big(f(A) \big) \Big] \subseteq Cl_{\delta} \Big[f^{-1} \big(f(A) \big) \Big]. \text{ It}$ implies that $Cl_{\delta} \Big[f(A) \Big] \subseteq f \Big[Cl_{\delta}(A) \Big].$

Thus $Cl_{\delta}\left[\left(f^{-1}\right)^{-1}(A)\right] \subseteq \left(f^{-1}\right)^{-1}\left[Cl_{\delta}(A)\right]$, for all $A \subseteq X$. Then by Theorem 2.8, it follows that f^{-1} is δ -*irresolute*.

(3) \Rightarrow (1): Let A be an arbitrary δ -closed set in X. Then X - A is δ -open in X. Since f^{-1} is δ -irresolute, $(f^{-1})^{-1}(X - A)$ is δ -open in Y. But $(f^{-1})^{-1}(X - A) = f(X - A) = Y - f(A)$.

Thus f(A) is δ -closed in Y. This shows that f is $pre-\delta$ -closed.

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