

for a function $f : \mathbb{R} \rightarrow \mathbb{R}$.

Note that the error term in (14) is dominated by

$$O\left(K^{D-1}x^{\frac{1}{2}}\right) + O\left(K^{-D-1}x^{2D+\frac{1}{2}}d^{-2D}\right).$$

Putting $K = x^\alpha$, $d = x^\beta$, and requiring that

$$\begin{aligned} \alpha D - \alpha + \frac{1}{2} &= \frac{3}{4}, \\ -\alpha D - \alpha + 2D + \frac{1}{2} - 2D\beta &= \frac{3}{4}, \end{aligned}$$

we find that $\alpha = \frac{1}{4(D-1)}$, $\beta = \frac{4D-5}{4D-4}$, i.e., that $K = x^{\frac{1}{4(D-1)}}$, $d = x^{\frac{4D-5}{4D-4}}$.

Thus, the error term $O\left(x^{\frac{3}{4}}\right)$ in (13) follows as required.

In [13] and [5], the authors applied the method developed in [14] and [15] for compact Riemann surfaces.

The method described in this paper is very well applied in [12], [1], [9], and [7] in the case of real hyperbolic manifolds with cusps, compact, odd-dimensional, real hyperbolic spaces, and compact, even-dimensional locally symmetric Riemannian manifolds of strictly negative curvature, respectively.

In order to derive their results, the authors usually apply approximate formulas for the logarithmic derivative of the corresponding zeta function, such as the Riemann or the Selberg, or the Ruelle zeta function (see, [16], [11], [8], [2]).

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