

$$\tau_{l,\alpha} = \frac{dU_l(z)}{dz} \Big|_{z=1} = \frac{1 - \left(\frac{p_\alpha}{1-\varepsilon q_\alpha}\right)^l}{(1-p_\alpha - \varepsilon q_\alpha) \left(\frac{p_\alpha}{1-\varepsilon q_\alpha}\right)^l} < \infty,$$

$$\alpha = \overline{1; \bar{k}}.$$

Now let m be fixed and $l \rightarrow \infty$ ($n = l + m - 1 \rightarrow \infty$). Then, renumbering the state of the automaton in the reverse order, it is easy to verify that the generating function of the probability of changing the action is a solution of the boundary value problem (9), if in it we replace l by m , p by r and r by p .

The solution obtained has the following form

$$U_m(z) = \frac{(1 - r_\alpha z - \varepsilon q_\alpha z) \left(\frac{r_\alpha z}{1-\varepsilon q_\alpha z}\right)^m}{1 - z + (1 - r_\alpha - \varepsilon q_\alpha) z \left(\frac{r_\alpha z}{1-\varepsilon q_\alpha z}\right)^m}$$

and

$$\sigma_{m,\alpha} = U_m(1) = 1, \tag{11}$$

$$\tau_{m,\alpha} = \frac{dU_m(z)}{dz} \Big|_{z=1} = \frac{1 - \left(\frac{p_\alpha}{1-\varepsilon q_\alpha}\right)^m}{(1-p_\alpha - \varepsilon q_\alpha) \left(\frac{p_\alpha}{1-\varepsilon q_\alpha}\right)^m} < \infty,$$

$$\alpha = \overline{1; \bar{k}}.$$

If $l \rightarrow \infty$ and $m \rightarrow \infty$, then the infinite automaton remains forever in that subset of states in which it was at the initial instant of time. In this case $U_l(z) = 0$ and

$$\sigma_{l,\alpha} = 0, \quad \tau_{l,\alpha} = \infty.$$

Passing to the limit in (7), we obtain that

$$\lim_{m \rightarrow \infty} U_l^{(n)}(z) = U_l(z), \quad \lim_{l \rightarrow \infty} U_l^{(n)}(z) = U_m(z),$$

$$\lim_{m \rightarrow \infty} \lim_{l \rightarrow \infty} U_l^{(n)}(z) = U_l(z) = 0.$$

Thus, by the continuity theorem [7], the sequence of finite automata $\{T_{kn,k}(l, m; \varepsilon)\}_{l=1}^\infty$, $\{T_{kn,k}(l, m; \varepsilon)\}_{m=1}^\infty$ and $\{T_{kn,k}(l, m; \varepsilon)\}_{l,m=1}^\infty$ converges to the corresponding limit automata $T_k(\infty, m; \varepsilon)$, $T_k(l, \infty; \varepsilon)$ and $T_k(\infty, \infty; \varepsilon)$ of the same structure and, according to [4], the asymptotic behavior of the finite automaton $T_{kn,k}(l, m; \varepsilon)$ in a stationary random environment $C(a_1, r_1; a_2, r_2; \dots; a_k, r_k)$ is determined by the behavior of the corresponding limit automaton $T_k(l, m; \varepsilon)$.

IV. CONCLUSION

Analyzing formulas (8), (10), (11) and taking into account Definition 2, with respect to the behavior of the automata $T_{kn,k}(l, m; \varepsilon)$ and $T_k(l, m; \varepsilon)$ in a stationary random environment $C(a_1, r_1; a_2, r_2; \dots; a_k, r_k)$, we can draw the following conclusion.

□. The behavior of a finite stochastic automaton $T_{kn,k}(l, m; \varepsilon)$ in a stationary random environment $C(a_1, r_1; a_2, r_2; \dots; a_k, r_k)$ is:

1. expedient if

$$\left\{ \begin{array}{l} p_1 - p_\alpha \leq \varepsilon(q_\alpha p_1 - q_1 p_\alpha) \\ r_1 - r_\alpha \leq \varepsilon(q_\alpha r_1 - q_1 r_\alpha) \end{array} \right\}, \quad \alpha = \overline{2; \bar{k}}. \tag{12}$$

at any finite integer values of the quantities l and m .

2. inexpedient if

$$\left\{ \begin{array}{l} p_1 - p_\alpha \geq \varepsilon(q_\alpha p_1 - q_1 p_\alpha) \\ r_1 - r_\alpha \geq \varepsilon(q_\alpha r_1 - q_1 r_\alpha) \end{array} \right\}, \quad \alpha = \overline{2; \bar{k}}. \tag{13}$$

at any finite integer values of the quantities l and m .

It should be noted that in expressions (13) and (14)

both inequalities are not weak at the same time.

3. indifferent if

$$\left\{ \begin{array}{l} p_1 - p_\alpha = \varepsilon(q_\alpha p_1 - q_1 p_\alpha) \\ r_1 - r_\alpha = \varepsilon(q_\alpha r_1 - q_1 r_\alpha) \end{array} \right\}, \quad \alpha = \overline{2; \bar{k}}. \tag{14}$$

4. If (12) or (13) are not satisfied, then the behavior of the automaton $T_{kn,k}(l, m; \varepsilon)$ in a stationary random environment $C(a_1, r_1; a_2, r_2; \dots; a_k, r_k)$ can be either expedient either inexpedient.

□. The behavior of an infinite stochastic automaton $T_k(l, \infty; \varepsilon)$ in a stationary random environment $C(a_1, r_1; a_2, r_2; \dots; a_k, r_k)$ is expedient if

$$p_1 - p_\alpha < \varepsilon(q_\alpha p_1 - q_1 p_\alpha), \quad \alpha = \overline{2; \bar{k}} \tag{15}$$

at any finite integer values of the quantity l .

□. The behavior of an infinite stochastic automaton $T_k(\infty, m; \varepsilon)$ in a stationary random environment $C(a_1, r_1; a_2, r_2; \dots; a_k, r_k)$ is expedient if

$$r_1 - r_\alpha < \varepsilon(q_\alpha r_1 - q_1 r_\alpha), \quad \alpha = \overline{2; \bar{k}} \tag{16}$$

at any finite integer values of the quantity m .

□V. The behavior of an infinite stochastic automaton $T_k(\infty, \infty; \varepsilon)$ in any stationary random environment $C(a_1, r_1; a_2, r_2; \dots; a_k, r_k)$ is indifferent.

According to [4], the asymptotic behavior of the finite stochastic automaton $T_{kn,k}(l, m; \varepsilon)$ is completely determined by the behavior of the corresponding infinite automaton $T_k(l, m; \varepsilon)$.

In conclusion, we note that the stochastic automaton $T_{kn,k}(l, m; \varepsilon)$, at integer of the values of the parameter ε ($\varepsilon = 0$ or $\varepsilon = 1$) is a deterministic automaton. Consequently, from (12) - (16) we obtain the condition for the expedient behavior of these automata.

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